#### Solution of Systems of Linear Equations and Applications with MATLAB® :

#### **II - Indirect Methods**

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### **Iterative Solution**

 Good for large systems of equations when Gauss elimination is NOT good,

i.e., if  $n \ge m$  for  $|A_{m,n}| |x_{n,1}| = |y_{m,1}|$ 

- (# unknowns is very large compared to # equations)
- Simple programming
- Applicable to nonlinear coefficients
- Requires an initial guess to start the iteration
- The goal is to:
  - Choose a good initial guess x0 for x
  - Substitute x0 in the equations and check if the right hand side of equations is equal to the left hand side or if x-x0<ε
  - Increment/decrement x0 until all equations are satisfied

## **Iterative Solution**

- Popular technique for finding roots of equations
- Applied to systems of linear equations to produce accurate results (Generalized *fixed point iteration*)
- Jacobi iteration: <u>Carl Jacobi</u> (1804-1851)
- Gauss-Seidel iteration: Johann Carl Friedrich Gauss (1777-1855) and Philipp Ludwig von Seidel (1821-1896)

### Quotations

It is true that Fourier had the opinion that the principal aim of mathematics was public utility and explanation of natural phenomena; but a philosopher like him should have known that the sole end of science is the honor of the human mind, and that under this title a question about numbers is worth as much as a question about the system of the world. Quoted in N Rose *Mathematical Maxims and Minims* (Raleigh N C

1988). Carl Jacobi

There are problems to whose solution I would attach an infinitely greater importance than to those of mathematics, for example touching ethics, or our relation to God, or concerning our destiny and our future; but their solution lies wholly beyond us and completely outside the province of science. Quoted in J R Newman, *The World of Mathematics* (New York 1956). Carl Friedrich Gauss

# A x = y Solution by Iteration

Start

Read  $x\theta$ 

 $\boldsymbol{X}$ 

f(x) = x - x0

End

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Input an initial guess for iteration to get started Can be any arbitrary vector x0 Ex: null vector x0=zeros(m,1)  $x_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ 



Iteration does not always converge!

# A x = y Solution by Iteration: Convergence

Sufficient condition for iteration to converge:

Matrix A should be diagonally dominant,

for all i:

$$a_{i,i} \Big| > \sum_{j=1, j \neq i}^n \Big| a_{i,j} \Big|$$

$$|a_{i,i}| > \sum_{j=1}^{i-1} |a_{i,j}| + \sum_{j=i+1}^{n} |a_{i,j}|$$

i.e. diagonal elements are larger in absolute value than the sum of the absolute value of other coefficients

or

If A is irreducible (no part of the equation can be solved independently of the rest) for all i

# Is it diagonally dominant?





# A x = y Solution by Iteration: Convergence

The iterative solution described here converges *unconditionally* if

for a *nonsingular matrix*, applied after premultiplying the equation Ax=y by A<sup>t</sup>.

$$A^t A x = A^t y$$

# Ex: Diagonally Dominant Matrix

Set of equations given by: (1)  $10x_1 - 2x_2 + 5x_3 = 8$ (2)  $x_1 + 7x_2 - 3x_3 = 10$ (3)  $-4x_1 - 2x_2 - 8x_3 = -20$ is predominantly diagonal as:

|10| > |-2| + |5||7| > |1| + |-3||-8| > |-4| + |-2|

Ax = y $\rightarrow \left( \begin{array}{ccc} 10 & -2 & 5 \\ 1 & 7 & -3 \\ -4 & -2 & -8 \end{array} \right) \left( \begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array} \right) = \left( \begin{array}{c} 8 \\ 10 \\ -20 \end{array} \right)$ 

Unknown variables on the diagonal are given by:

$$x_{1} = \frac{8 - (-2x_{2} + 5x_{3})}{10}$$
$$x_{2} = \frac{10 - (x_{1} - 3x_{3})}{7}$$
$$x_{3} = \frac{-20 - (-4x_{1} - 2x_{2})}{-8}$$

# A x = y Solution by Iteration: Convergence

Read  $x\theta$ 

 $x\theta = x$ 

 $\boldsymbol{X}$ 

f(x) = x - x0

End

3>

Initial guess values are used to calculate new guess values
New estimates of x are calculated
Iteration continues until convergence is satisfied, i.e. *f(x)<ε* ε : convergence criteria (tolerance)

Jacobi (Simple) Iteration (1) $a_{1,1}x_1 + a_{1,2}x_2 + \ldots + a_{1,n}x_n = y_1$ (2) $a_{2.1}x_1 + a_{2.2}x_2 + \ldots + a_{2.n}x_n = y_2$ • • (n) $a_{n,1}x_1 + a_{n,2}x_2 + \ldots + a_{n,n}x_n = y_n$  $\sum_{i,j} a_{i,j} x_j = y_i$ , where i = 1, 2, ..., n. Extracting  $x_i$  yields  $a_{i,i} x_i + \sum_{i,j} a_{i,j} x_j = y_i$ Solving for  $x_i$  gives:  $x_i = \frac{1}{a_{i,i}} \left( y_i - \sum_{\substack{j=1 \ i \neq i}}^n a_{i,j} x_j \right)$ Consequently, the iterative scheme should be  $x_i \leftarrow \frac{1}{a_{i,i}} \left( y_i - \sum_{j=1}^n a_{i,j} x_j \right)$ 

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# Jacobi (Simple) Iteration

Iteration cycle:

- Choose a starting vector x0 (Initial guesses)
- If a good guess for solution is not available, choose x randomly

Use 
$$x_i \leftarrow \frac{1}{a_{i,i}} \left( y_i - \sum_{\substack{j=1\\j \neq i}}^n a_{i,j} x_j \right)$$

with  $x_i = x0$ 

to recompute each value of x

4. Check if  $|x-x0| \le (tolerance)$ , if so x=x0

5. If  $|x-x0| \ge \varepsilon$ , assign new values to x0

Repeat this cycle until changes in x (x-x0) between successive iteration cycles become sufficiently small, i.e,  $|x-x0| \le \varepsilon$ 

# Jacobi (Simple) Iteration

$$\begin{aligned} x_i^{(t)} &= \frac{1}{a_{i,i}} \left( y_i - \sum_{\substack{j=1\\j\neq i}}^n a_{i,j} x_j^{(t-1)} \right), \text{ where t is the iteration count} \\ \text{for } t=1 \\ x_i^{(1)} &= \frac{1}{a_{i,i}} \left( y_i - \sum_{\substack{j=1\\j\neq i}}^n a_{i,j} x_j^{(0)} \right), \text{ where } x_j^{(0)} \text{ is the initial guess x0} \\ \text{if } \left| x_i^{(1)} - x_i^{(0)} \right| > \varepsilon, \\ x_i^{(2)} &= \frac{1}{a_{i,i}} \left( y_i - \sum_{\substack{j=1\\j\neq i}}^n a_{i,j} x_j^{(1)} \right) \\ \text{ continue iteration until } \left| x_i^{(t)} - x_i^{(t-1)} \right| \le \varepsilon \text{ or } \left| y_i - \left( a_{i,i} x_i^{(t)} - \sum_{\substack{j=1\\j\neq i}}^n a_{i,j} x_j^{(t)} \right) \right| \le \delta \end{aligned}$$

### Ex: Jacobi (Simple) Iteration

(1)  $4x_1 - 2x_2 + x_3 = 3$ (2)  $3x_1 - 7x_2 + 3x_3 = -2$ (3)  $x_1 + 3x_2 - 5x_3 = -8$ 

$$x_{1} + 3x_{2} - 5x_{3} = -8$$

$$= \frac{3 - (-2x_{2} + x_{3})}{4}$$

$$= \frac{-2 - (3x_{1} + 3x_{3})}{-7}$$

$$= \frac{-8 - (x_{1} + 3x_{3})}{-7}$$

 $X_1$ 

 $X_{2}$ 

 $x_{3} =$ 

$$>> x0 = zeros(n,1)$$
  
x0 =  
0  
0  
0

 $\begin{vmatrix} x & -2 & 1 \\ 3 & -7 & 3 \\ 1 & 3 & -5 \end{vmatrix} \begin{vmatrix} x_1 \\ x_2 \\ x \end{vmatrix} =$ 

1.600000000000000

t = 2

-2

 $x = 0.49285714285714 \\ 0.28571428571429 \\ 1.6000000000000$ 

$$t = 2$$

 $\begin{array}{rl} x = & 0.49285714285714 \\ & 1.29285714285714 \\ & 1.600000000000 \end{array}$ 

 $\begin{array}{rl} x = & 0.49285714285714 \\ & 1.29285714285714 \\ & 1.92142857142857 \end{array}$ 

### Ex: Jacobi (Simple) Iteration

```
%Solve 3 strictly diagonally dominant linear equations for 3 unknowns: Jacobi iteration
a=[4 -2 1;3 -7 3;1 3 -5]; %Coefficient matrix
                         % Vector for values of f(x) = ax
y=[3;-2;-8];
n=length(y);
x = zeros(n, 1);
                         %Create an empty matrix for x
                         %Initial guess values for x
x0=x;
                         %Set max iteration no to stop iteration if system does not converge
tmax=50;
tol=10^-3;
                         %Set the tolerance to end iteration before t=tmax
for t=1:tmax,
                         %Start iteration
  for j=1:n,
          x(j) = (y(j)-a(j,[1:j-1,j+1:n])*x0([1:j-1,j+1:n]))/a(j,j);
  end
  error=abs(x-x0); x0=x;
  if error<=tol
     'Convergence is good. Iteration ended before tmax '
     break
  end
end
display('Iteration no='); display(t-1);
Х
```

### Ex: Jacobi (Simple) Iteration

# Results of the Jacobi iteration in the command window:

ans =

Convergence is good. Iteration ended before tmax Iteration no=

ans =

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#### $_{\rm X} =$

1.00011187524906 1.99949883459545 2.99983186316654 Direct solution by Gauss elimination in the command window: >> x=a yx =1 2 3

#### **Gauss-Siedel Iteration**

Iteration cycle:

- Choose a starting vector x0 (Initial guesses)
- If a good guess for solution is not available, choose x randomly

Use 
$$x_i^{(t)} \leftarrow \frac{1}{a_{i,i}} \left( y_i - \sum_{j=1}^{i-1} a_{i,j} x_j^{(t)} - \sum_{j=i+1}^n a_{i,j} x_j^{(t-1)} \right)$$
 to

to compute each

element of x, always using the latest available values ox  $x_i$ 

- Helps accelerate convergence
- Simplifies programming as the new values can be written over the old ones

#### **Gauss-Siedel Iteration**

$$\begin{aligned} x_{i}^{(t)} &= \frac{1}{a_{i,i}} \left( y_{i} - \sum_{j=1}^{i-1} a_{i,j} x_{j}^{(t)} - \sum_{j=i+1}^{n} a_{i,j} x_{j}^{(t-1)} \right), \text{ where t is the iteration count} \\ \text{for } t=1 \\ x_{i}^{(1)} &= \frac{1}{a_{i,i}} \left( y_{i} - \sum_{j=1}^{i-1} a_{i,j} x_{j}^{(1)} - \sum_{j=i+1}^{n} a_{i,j} x_{j}^{(0)} \right), \text{ where } x_{j}^{(0)} \text{ is the initial guess x0} \\ \text{and } x_{j}^{(1)} \text{ is the updated value calculated using } x_{j}^{(0)} \\ \text{if } \left| x_{i}^{(1)} - x_{i}^{(0)} \right| > \varepsilon, \\ x_{i}^{(2)} &= \frac{1}{a_{i,i}} \left( y_{i} - \sum_{j=1}^{i-1} a_{i,j} x_{j}^{(2)} - \sum_{j=i+1}^{n} a_{i,j} x_{j}^{(1)} \right) \\ \text{ continue iteration until } \left| x_{i}^{(t)} - x_{i}^{(t-1)} \right| \le \varepsilon \text{ or } \left| y_{i} - \left( a_{i,i} x_{i}^{(t)} - \sum_{j=i+1}^{i-1} a_{i,j} x_{j}^{(t-1)} - \sum_{j=i+1}^{n} a_{i,j} x_{j}^{(t-1)} \right) \right| \le \delta \end{aligned}$$

### Gauss-Siedel Iteration with Relaxation: Successive Over Relaxation

To improve the convergence of Gauss-Siedel method using relaxation:

• Take the new value of  $x_i$  as a weighted average of its previous value and the predicted/calculated value

$$x_{i}^{(t)} = \omega \frac{1}{a_{i,i}} \left( y_{i} - \sum_{j=1}^{i-1} a_{i,j} x_{j}^{(t)} - \sum_{j=i+1}^{n} a_{i,j} x_{j}^{(t-1)} \right) + (1 - \omega) x_{i}^{(t-1)},$$
where

where

- t : iteration count
- $\omega$ : over-relaxation parameter satisfying  $1 \le \omega < 2$

#### If $\omega=1$ , the SOR reduces to the Gauss-Siedel method

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#### Successive Over-Relaxation: SOR

- If  $\omega = 1$ , no relaxation
- If  $\omega$ <1, under-relaxation, i.e. interpolation between the old  $x_i$  and the calculated  $x_i$
- If  $\omega > 1$ , over-relaxation, i.e. extrapolation
- A good estimate for an optimal value of ω can be computed during run time:

Let  $\Delta x^{(k)} = |x^{(k-1)} - x^{(k)}|$  be the magnitude of the change in x during the k<sup>th</sup> iteration for  $\omega = 1$  (without relaxation) If k is sufficiently large, say  $k \ge 5$ 

$$\omega_{opt} \approx \frac{2}{1 + \sqrt{1 - \left(\frac{\Delta x^{(k+p)}}{\Delta x^{(k)}}\right)^{\frac{1}{p}}}}$$
, where p is a positive integer

#### Ex: Gauss-Siedel with Relaxation (SOR)

```
%Solve 3 linear equations that are strictly diagonally dominant
% for 3 unknowns using SOR iteration
a=[4 - 2 1; 3 - 7 3; 1 3 - 5]; %Vector for values of f(x)=ax
y=[3;-2;-8];
                     % Vector for values of f(x) = ax
n=length(y);
x = zeros(1,n);
                            %Create an empty matrix for x
w=1.2;
                            %Relaxation constant
for t=1:50,
  error=0;
   for i=1:n,
     s=0; xb=x(i);
     for j=1:n,
       if i \sim = j, s = s + a(i,j) * x(j); end,
     end
     x(i) = w^{*}(v(i)-s)/a(i,i) + (1-w)^{*}x(i);
     error=error+abs(x(i)-xb);
  end
   fprintf('Iteration no = \%3.0f, error = \%7.2e \n', t, error)
  if error/n < 10^{-4}, break; end
end,
          Х
```

#### Ex Cont<sup>d</sup>.: Successive Over-Relaxation

Iteration no = 1, error = 4.42e+000Iteration no = 2, error = 1.52e+000Iteration no = 3, error = 1.12e+000Iteration no = 4, error = 2.13e-001Iteration no = 5, error = 9.29e-002Iteration no = 6, error = 3.20e-002Iteration no = 7, error = 1.21e-002Iteration no = 8, error = 4.42e-003Iteration no = 9, error = 1.63e-003Iteration no = 10, error = 5.99e-004Iteration no = 11, error = 2.20e-004

 $_{\rm X} =$ 

1.00004015934601 1.99999668943987 3.00001586803950