## Design Patterns

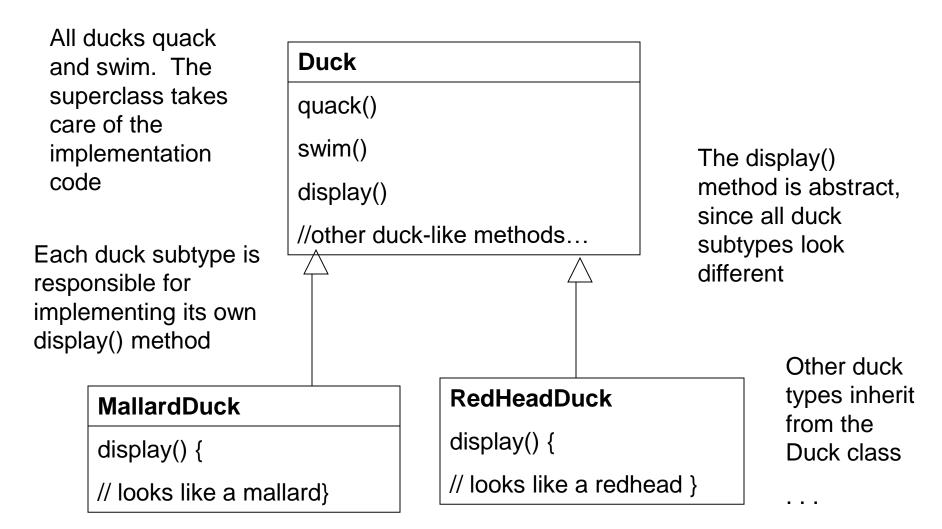
#### Strategy Pattern\* How to design for flexibility?

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\*revised from, www.uwosh.edu/faculty\_staff/huen/262/f09/slides/10\_Strategy\_Pattern.ppt

## Existing Duck application



## Testing Mallard, RedHeadDuck classes

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🚰 BlueJ: Terminal Window - Strategy0

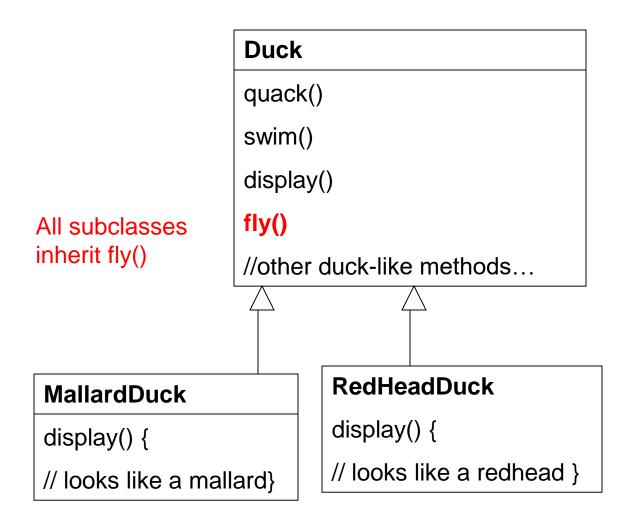
Options

- I say quack-quack
- I'm a real Mallard duck
- I say quack-quack
- I'm a real Red Headed duck

#### Changing Requirment

- No sweat!
  - Add a method fly() in Duck
  - Continue to use inheritance

## Add a method fly() in Duck



#### Executing

🐴 Blue J: Terminal Window - Strategy 1

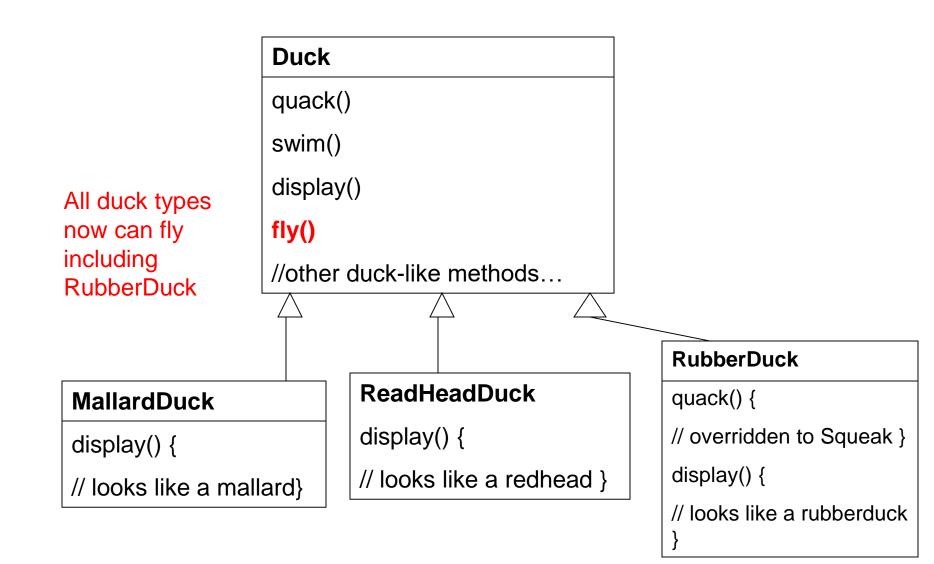
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#### Options.

I say quack-quack All ducks float, even decoys! See me flap my wings I'm a real Mallard duck

I say quack-quack All ducks float, even decoys! See me flap my wings I'm a real Red Headed duck

## Something seriously wrong!



#### Executing ... What?

#### 🚰 BlueJ: Terminal Window - Strategy2

#### Options

I say quack-quack All ducks float, even decoys! See me flap my wings I'm a real Mallard duck

I say quack-quack All ducks float, even decoys! See me flap my wings I'm a real Red Headed duck

I say squeak-squeak All ducks float, even decoys! See me flap my wings I'm a rubber duckie

#### Root cause?

- Applying inheritance to achieve re-use
- Poor solution for maintenance

#### How do we fix this?

- Using inheritance as before
  - Override the fly() method in rubber duck as in quack()

#### Executing

#### 🚰 Blue J: Terminal Window - Strategy 3

#### Options

I say quack-quack All ducks float, even decoys! See me flap my wings I'm a real Mallard duck

I say quack-quack All ducks float, even decoys! See me flap my wings I'm a real Red Headed duck

```
I say squeak-squeak
All ducks float, even decoys!
I cannot fly
I'm a rubber duckie
```

#### Is the problem solved?

• Any new problems?

#### Wait a minute

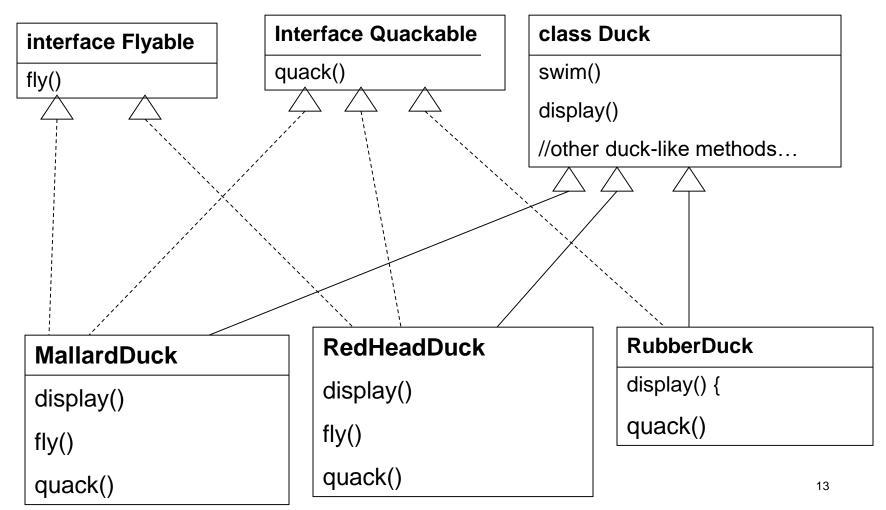
- How about new duck types?
  - Decoy duck?
    - Can't quack
    - Can't fly
- How do we solve it?

#### Summary

- What have we done so far?
- What problems have we solved?
- What problems have we introduced in solving the problems?
- Is there a better way of doing things?

#### How about Interface?

- Take the fly() method out of Duck superclass
- And make a Flyable() interface
  - Only those ducks that fly are required to implement the interface
- Make a Quackable interface too





- You shoot yourself in the foot by <u>duplicating code</u> for every duck type that can fly and quack!
- And we have a lot of duck types
- We have to be careful about the properties we cannot just call the methods blindly
- We have created a maintenance nightmare!

## Re-thinking:

- Inheritance has not worked well because
  - Duck behavior keeps changing
  - Not suitable for all subclasses to have those properties
- Interface was at first promising, but
  - No code re-use
  - Tedious
    - Every time a behavior is changed, you must track down and change it in all the subclasses where it is defined
  - Error prone

#### #1 Design Principle

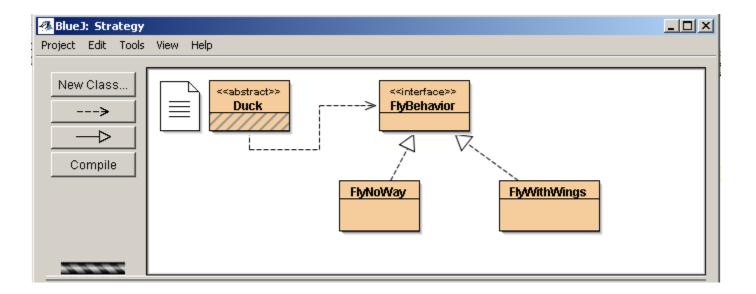
- Identify the aspects of your application that <u>vary</u> and separate them from what stays the same
- So what are variable in the Duck class?
  - Flying behavior
  - Quacking behavior
- Pull these duck behaviors out of the Duck class
  - Create new classes for these behaviors

# How do we design the classes to implement the fly and quack behaviors?

- Goal: to keep things flexible
- Want to assign behaviors to instances of Duck
  - Instantiate a new MallardDuck instance
  - Initialize it with a specific type of flying
  - Be able to change the behavior dynamically

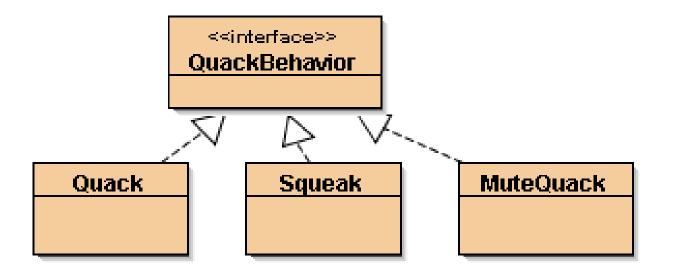
#### #2 Design Principle

- Program to a supertype, not an implementation
- Use a supertype to represent each behavior
  - FlyBehavior and QuackBehavior
  - Each implementation of a behavior will implement one of these supertypes
- In the past, we rely on an implementation
  - In superclass Duck, or
  - A specialized implementation in the subclass
- Now: Duck subclass will use a behavior represented in a supertype.



#### 3 classes in code

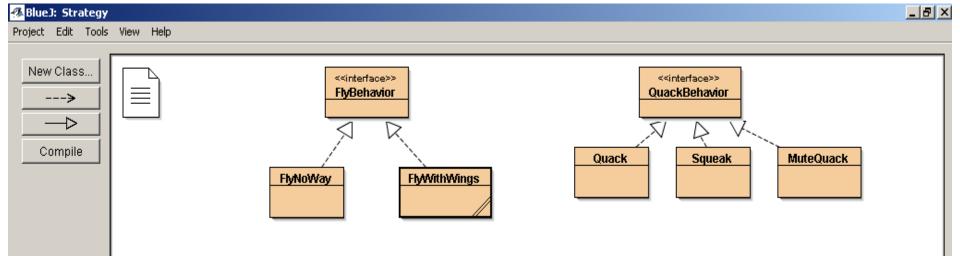
```
public interface FlyBehavior {
  public void fly();
public class FlyWithWings implements FlyBehavior {
  public void fly() {
        System.out.println("I'm flying!!");
public class FlyNoWay implements FlyBehavior {
  public void fly() {
       System.out.println("I can't fly");
```



```
public interface QuackBehavior {
        public void quack();
}
```

#### Specific behaviors by implementing interface QuackBehavior

```
public class Quack implements QuackBehavior {
  public void quack() {
        System.out.println("Quack");
public class Squeak implements QuackBehavior {
  public void quack() {
        System.out.println("Squeak");
  }
public class MuteQuack implements QuackBehavior {
  public void quack() {
        System.out.println("<< Silence >>");
```



#### Integrating the Duck Behavior

1. Add 2 instance variables:

Behavior variables are declared as the behavior SUPERTYPE	Duck	Instance variables hold a reference to a specific behavior at runtime
	FlyBehavior flyBehavior	
	QuackBehavior quackBehavior	
These general methods replace fly() and quack()	performQuack()	
	Swim()	
	Display()	
	performFly()	
	//OTHER duck-like methods	

#### 2. Implement performQuack()

public abstract class Duck {

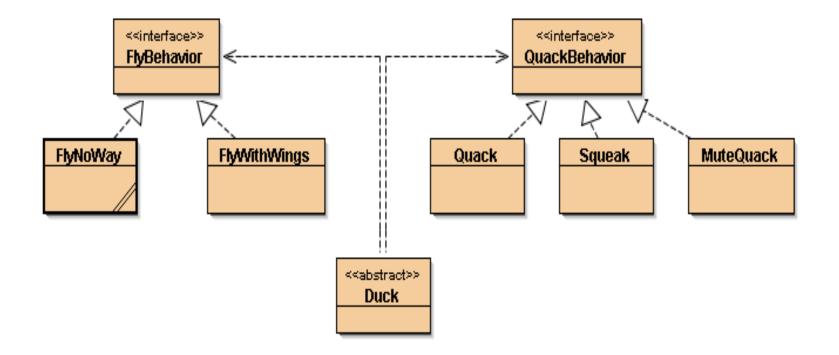
// Declare two reference variables for the behavior interface types
FlyBehavior flyBehavior;

QuackBehavior quackBehavior; // All duck subclasses inherit these // etc

```
public Duck(FlyBehavior f, QuackBehavior q) {
}
```

```
public Duck() {
}
```

```
public void performQuack() {
    quackBehavior.quack(); // Delegate to the behavior class
}
```



# 3. How to set the quackBehavior variable & flyBehavior variable

public class MallardDuck extends Duck {

```
public MallardDuck() {
```

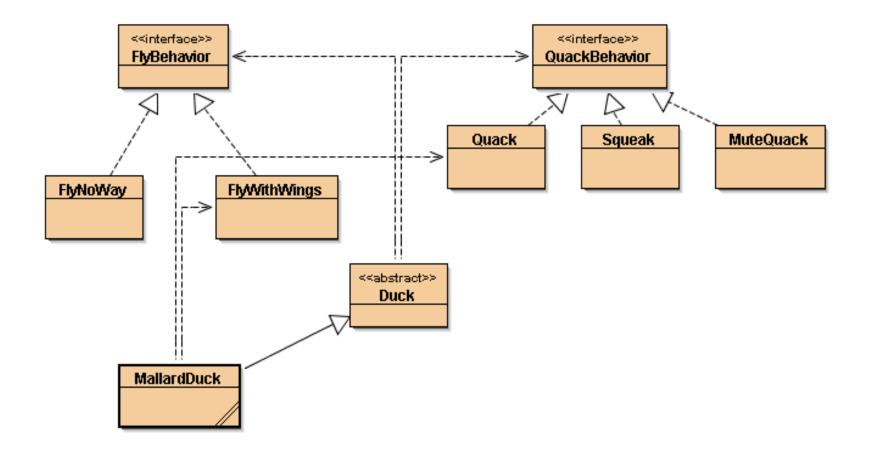
```
quackBehavior = new Quack();
    // A MallardDuck uses the Quack class to handle its quack,
    // so when performQuack is called, the responsibility for the quack
    // is delegated to the Quack object and we get a real quack
    flyBehavior = new FlyWithWings();
    // And it uses flyWithWings as its flyBehavior type
```

```
public void display() {
```

}

}

```
System.out.println("I'm a real Mallard duck");
```



#### Testing the Duck code

Type and compile:

- Duck class and the MallardDuck class
- FlyBehavior interface and the two behavior implementation classes (FlyWithwings.java and flyNoWay.java)
- QuackBehavior interface and 3 behavior implementation classes
- Test class (MiniDuckSimulator.java)

#### // 1. Duck class

public abstract class Duck {

// Reference variables for the behavior interface types

FlyBehavior flyBehavior;

QuackBehavior quackBehavior; // All duck subclasses inherit these

```
public Duck() { }
```

```
abstract void display();
```

```
public void performFly() {
flyBehavior.fly(); // Delegate to the behavior class
```

```
public void performQuack() {
    quackBehavior.quack(); // Delegate to the behavior class
}
```

```
public void swim() {
    System.out.println("All ducks float, even decoys!");
```

Is it possible to manage all duck's sub-object with this super type? 2. FlyBehavior and two behavior implementation classes

```
public interface FlyBehavior {
  public void fly();
public class FlyWithWings implements FlyBehavior {
  public void fly() {
        System.out.println("I'm flying!!");
public class FlyNoWay implements FlyBehavior {
  public void fly() {
        System.out.println("I can't fly");
```

#### // 3. QuackBehavior interface and 3 behavior implementation classes

```
public interface QuackBehavior {
  public void quack();
public class Quack implements QuackBehavior {
  public void quack() {
        System.out.println("Quack");
  }
                  _____
public class Squeak implements QuackBehavior {
  public void quack() {
        System.out.println("Squeak");
  }
public class MuteQuack implements QuackBehavior {
  public void quack() {
        System.out.println("<< Silence >>");
  }
```

## 4. Type and compile the test class (MiniDuckSimulator.java)

public class MiniDuckSimulator {

public static void main(String[] args) {

Duck mallard = new MallardDuck(); mallard.performQuack();

// This calls the MallardDuck's inherited performQuack() method,

// which then delegates to the object's QuackBehavior

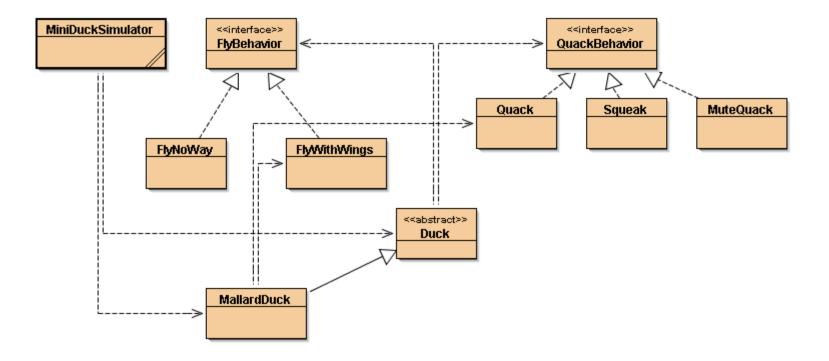
// (i.e. calls quack() on the duck's inherited quackBehavior

// reference)

mallard.performFly();

// Then we do the same thing with MallardDuck's inherited
// performFly() method.

#### At the end: Strategy project



#### Check-in

- We have built dynamic behavior in ducks e.g. a MallardDuck
  - The dynamic behavior is instantiated in the duck's constructor
- How can we change the duck's behavior after instantiation?

### Changing a duck's behavior after instantiation

 Set the duck's behavior type through a mutator method on the duck's subclass

## How to set behavior dynamically?

}

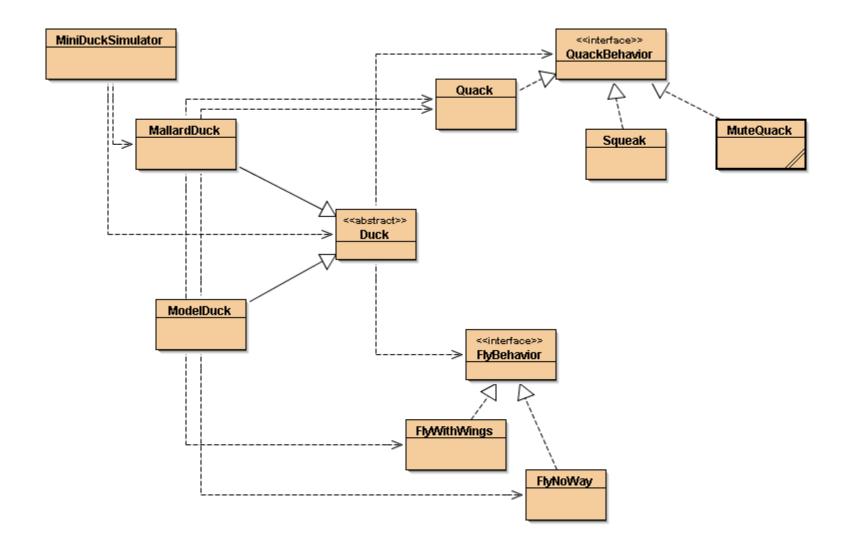
1. Add new methods to the Duck class public void setFlyBehavior (FlyBehavior fb) { flyBehavior = fb; }

```
public void setQuackBehavior(QuackBehavior qb) {
  quackBehavior = qb;
```

# 2. Make a new Duck type (ModelDuck.java)

```
public class ModelDuck extends Duck {
  public ModelDuck() {
    flyBehavior = new FlyNoWay();
    // Model duck has no way to fly
    quackBehavior = new Quack();
}
```

public void display() {
 System.out.println("I'm a model duck");



## Enabling ModelDuck to fly

• Use a mutator (setter) method to enable ModelDuck to fly

3. Make a new FlyBehavior type (FlyRocketPowered.java)

public class FlyRocketPowered implements FlyBehavior {

```
public void fly() {
    System.out.println("I'm flying with a rocket");
}
```

4. Change the test class (MiniDuckSimulator.java), add the ModelDuck, and make the ModelDuck rocket-enabled

Duck model = new ModelDuck();

model.performFly();

// call to performFly() delegates to the flyBehavior

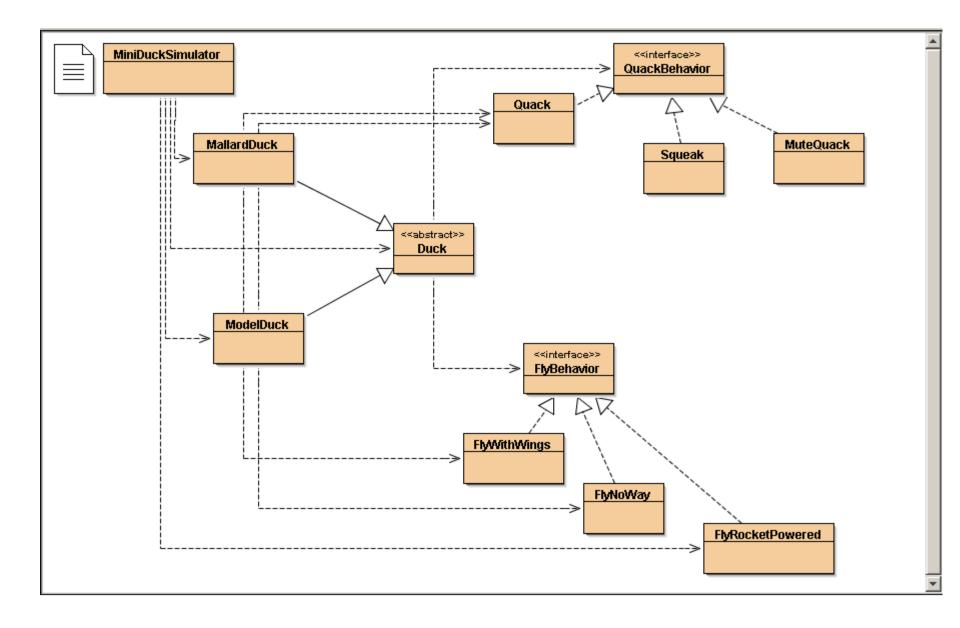
// object set in ModelDuck's constructor

model.setFlyBehavior(new FlyRocketPowered());

// change the duck's behavior at runtime by

- // invoking the model's inherited behavior setter
- // method

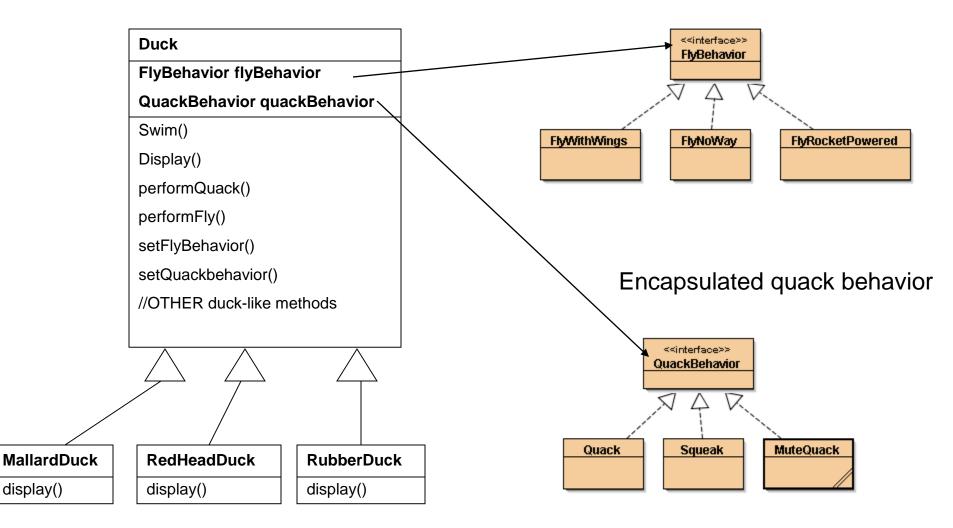
model.performFly();



# Big Picture on encapsulated behaviors

Reworked class structure

#### Encapsulated fly behavior



#### HAS-A can be better than IS-A

- Each duck <u>has a</u> FlyBehavior and a QuackBehavior to which it delegates flying and quacking
- <u>Composition</u> at work
  - Instead of inheriting behavior, ducks get their behavior by being *composed* with the right behavior object

## Third Design Principle

#### • Favor composition over inheritance

- More flexibility
- Encapsulate a family of algorithms into their own set of classes
- Able to change behavior at runtime

#### Strategy

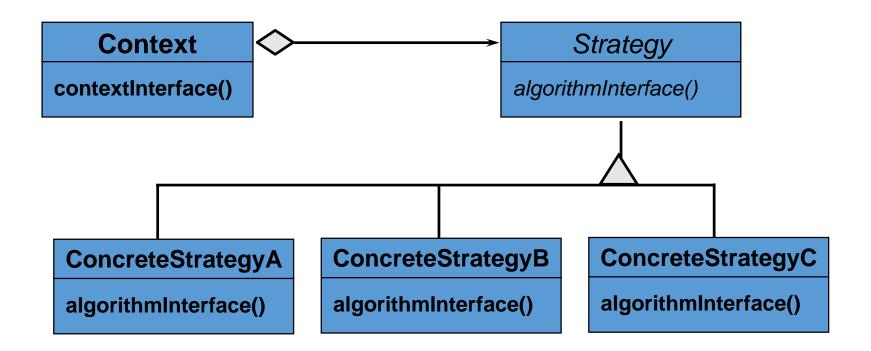
## In a Strategy design pattern, you will:

- Define a family of algorithms
- Encapsulate each one
- Make them interchangeable

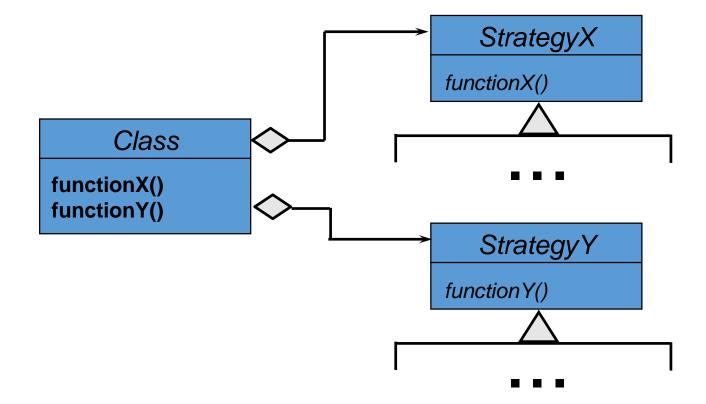
#### You should use Strategy when:

- You have code with a lot of algorithms
- You want to use these algorithms at different times
- You have algorithm(s) that use data the client should not know about

#### Strategy Class Diagram



Strategy makes this easy!



#### Benefits of Strategy

- Eliminates conditional statements
  - Can be more efficient than case statements
- Choice of implementation
  - Client can choose among different implementations with different space and time trade-offs
- Families of related algorithms
- Alternative to subclassing
  - This lets you vary the algorithm dynamically, which makes it easier to change and extend
  - You also avoid complex inheritance structures

#### Strategy Pattern

- The strategy Pattern
  - Defines a family of algorithms,
  - Encapsulates each one,
  - Makes them interchangeable.
- Strategy lets the algorithm vary independently from clients that use it

