Multi-technique comparison of troposphere zenith delays and gradients during CONT08

Kamil Teke ^(1,2), Johannes Böhm⁽¹⁾, Tobias Nilsson⁽¹⁾, Harald Schuh⁽¹⁾, Peter Steigenberger⁽³⁾, Rolf Dach⁽⁴⁾, Robert Heinkelmann⁽⁵⁾, Pascal Willis^{(6, 7),} Rüdiger Haas⁽⁸⁾, S. Garcia Espada^(8, 9), Thomas Hobiger⁽¹⁰⁾, Ryuichi Ichikawa⁽¹⁰⁾, Shingo Shimizu⁽¹¹⁾



TECHNISCHE UNIVERSITÄT MÜNCHEN



(1) Vienna University of Technology, Austria

(2) Hacettepe University, Turkey
(3) Technische Universität München, Germany
(4) University of Bern, Switzerland

(5) Deutsches Geodätisches Forschungsinstitut, Germany

(6) Institut Géographique National, France
(7) Institut de Physique du Globe de Paris, France
(8) Chalmers University of Technology, Sweden
(9) Instituto Geografico Nacional, Spain

(10) National Institute of Information and Communications Technology, Japan (11) National Research Institute for Earth Science and Disaster Prevention, Japan



b UNIVERSITÄT BERN













The aims of our study are

- Quantify agreement of troposphere estimates
- Figure out site and technique specific irregularities

Agreement criteria are

$$e.g. \quad x_{i} = ZTD_{i}^{VLBI-VieVS} \quad y_{i} = ZTD_{i}^{GPS-CODE} \quad \Delta_{i} = x_{i} - y_{i}$$

$$\overline{\Delta} = \frac{1}{n} \sum_{i=1}^{n} \Delta_{i} \qquad i = 1, 2, \cdots, n$$

$$Sx = \left[\frac{1}{n-1} \sum_{i=1}^{n} (\Delta_{i} - \overline{\Delta})^{2}\right]^{\frac{1}{2}}$$

$$r_{xy} = \frac{Cov(x, y)}{S_{x} S_{y}} = \frac{\sum_{i=1}^{n} (x_{i} - \overline{x})(y_{i} - \overline{y})}{\left[\sum_{i=1}^{n} (x_{i} - \overline{x})^{2} \cdot \sum_{i=1}^{n} (y_{i} - \overline{y})^{2}\right]^{\frac{1}{2}}} \qquad (p < 0.05)$$

CONTO8 co-located sites



first observation: Tuesday August 12, 2008 @ 00:00:00 UT last observation: Tuesday August 26, 2008 @ 23:59:59 UT

<u>Very Long Baseline Interferometry (VLBI)</u>

• <u>Vienna</u> <u>VLBI</u> <u>Software</u> (VieVS):

- NNT/NNR on ITRF2005.
- VMF1, above 5°.
- 0.7 picosec²/sec for ZTDs (relatively loose).
- 2 mm/day for gradients (relatively loose).
- 30 minutes for ZTDs, and 120 for gradients.
- APL applied a priori (Petrov and Boy, 2004)

<u>International VLBI Service for Geodesy and Astrometry</u> (IVS):

-Intra-technique combined solution for ZTDs and troposphere gradients. -60 minutes for ZTDs and for gradients

<u>Global Positioning System (GPS)</u>

- <u>Center for Orbit Determination in Europe (CODE)</u>
- Bernese GPS software.
- NNR on IGS05.
- 120 minutes interval for ZTDs and 24 h for gradients.
- VMF1, 3° + elevation dependent weighting.
- No constraints for zenith delays and gradients.
- APL applied.
- <u>I</u>nternational <u>G</u>NSS <u>Service</u> (IGS)
- GIPSY/Oasis software.
- PPP solution, Kalman filter.
- IGS final combined : orbits, clocks, and EOP.
- NMF, 7°.
- 5 minutes for ZTDs.
- Estimated parameters are: clocks, station position, zenith wet delay, troposphere gradients, phase biases (Byun S.H. and Bar-Sever Y.E., 2009).

<u>D</u>oppler <u>O</u>rbitography and <u>R</u>adio Positioning <u>I</u>ntegrated by <u>S</u>atellite (DORIS)

- <u>Institut Géographique National (IGN)</u>
- Software is GIPSY/Oasis.
- TRF is fixed to ign09d02.
- VMF1, 10°.
- DORIS reset at no regular interval.

- It is reset at start of pass and only if the previous reset is 20 minutes before or earlier.

- ZTD epochs interpolated linearly from the irregular epochs to 120 minutes (epochs at UTC integer hours).

- No interpolation between the data gaps larger than 60 minutes.

- Co-located sites are Ny-Ålesund (spjb), Kokee Park (kolb), Hartebeesthoek (hbmb).

<u>Water Vapor Radiometer (WVR)</u>

- Slant wet delays inferred from measurements of the sky brightness temperature at about 22 GHz and 31 GHz.

- ZWDs and gradients obtained by a least-squares fit. 30 minutes estimation interval for ZWDs and 120 minutes estimation intervals for troposphere gradients.

- ZHDs calculated from surface pressure measurements at the VLBI antenna.

- Cut off 20°.
- Data aquired during rain removed.
- Co-located sites: Wettzell, Tsukuba, and Onsala.

<u>Numerical Weather Models (NWMs)</u>

•Japan <u>M</u>eteorological <u>Ag</u>ency - <u>K</u>ashima <u>Ray-T</u>racing <u>T</u>ools (JMA-KARAT).

• <u>High Resolution Limited Area Model (HIRLAM)</u>.

•<u>E</u>uropean <u>C</u>entre for <u>M</u>edium-Range <u>W</u>eather <u>F</u>orecasts (ECMWF).

NWM	The regions for which the models provide data	Spatial resolution	Time Resolution (hours)	Number of levels at each profile	Troposphere gradients estimated ?
JMA-KARAT	Japan	0.1°	3	21	YES
HIRLAM	Europe	0.2°	3	40	NO
ECMWF	Global	0.25°	6	21	YES



















Biases of ZTDs between VieVS and other solutions



Std. dev. of ZTDs between VieVS and other solutions





















Conclusions

• ZTD estimates of space geodetic techniques (VLBI, GPS, DORIS) for different solutions (VieVS, IVS, IGN, IGS, CODE) generally agree at the 0.5-1 cm level.

• ZTD estimates of space geodetic techniques and other techniques/models (WVR, ECMWF, HIRLAM, JMA-KARAT) agree with each other better than 2 cm. Correlation coefficients are typically > 0.9 (not shown in the presentation).

 For both ZTDs and gradients the best agreement is found when doing an intra-technique comparison (e.g. VieVS and IVS, CODE and IGS).

•The best inter-technique agreement both for ZTD and gradient estimates is achieved between VLBI and GPS.

 Correlations of gradients between techniques are mostly below 0.6.

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