

# IVS-CONT08 Oturumları Boyunca Farklı Tekniklerden Elde Edilen Troposfer Zenit Sinyal Gecikmelerinin ve Gradyanlarının Karşılaştırılması



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# VLBI ölçülerinin analizinde troposfer sinyal gecikme modeli

$$\Delta\tau_{trop} = 10^{-6} \int_0^{H_{trop}} [N_h(s) + N_w(s)] ds$$

Troposfer gecikmesi lineer model:

$$\Delta\tau_{trop}(\alpha, \varepsilon) = ZHDm_h(\varepsilon) + ZWDm_w(\varepsilon) + m_w(\varepsilon)\cot(\varepsilon)[G_n \cos(\alpha) + G_e \sin(\alpha)]$$



Parametre kestirimi öncesi ölçü denklemlerinden indirgenir (Saastamoinen, 1972)



estimated



estimated



estimated

# Troposfer izdüşüm fonksiyonları

$$m_{h,w}(e) = \frac{1 + \frac{a_i}{1 + \frac{b_i}{1 + \frac{c_i}{1 + \dots}}}}{\sin(e) + \frac{a_i}{\sin(e) + \frac{b_i}{\sin(e) + \frac{c_i}{\sin(e) + \dots}}}}$$

e : Elevation cut off angle

$a_i, b_i, c_i, \dots = f(\varphi, H, \text{doy}, t, \alpha, \dots)$

$\varphi$  : station latitude

H : station orthometric height

doy : day of year

P : surface total pressure

t : surface temperature

$\alpha$  : tempreature lapse rate

Niell Mapping Function (NMF) (Niell, 1996)

Isobaric Mapping Function (IMF) (Niell, 2000)

Vienna Mapping Functions 1 (VMF1) (Boehm, Werl, Schuh, 2006)

Global Mapping Function (Boehm, Niell, Tregoning, Schuh, 2006)

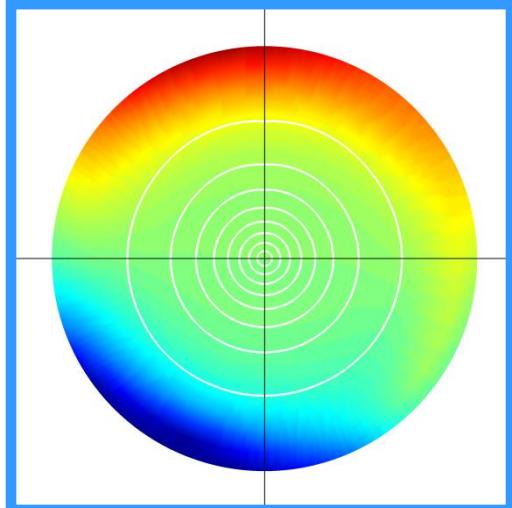
Some other mapping functions:

Chao, Lanyi, CfA, Ifadis, Davis, MTT, B&E, F&K, UNBabc, UNBab

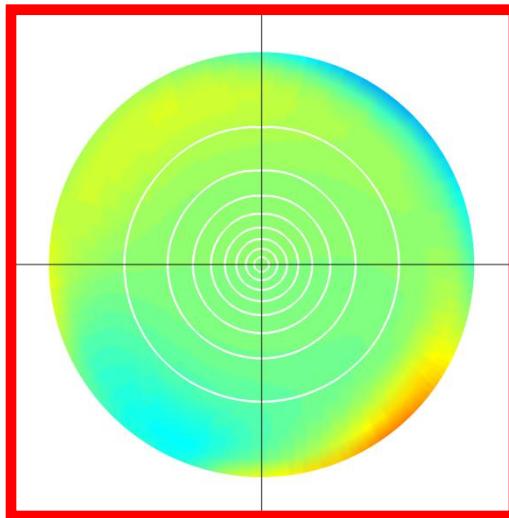
# Modeling azimuthal asymmetries

„classical“ gradients (IERS Conventions 2010)

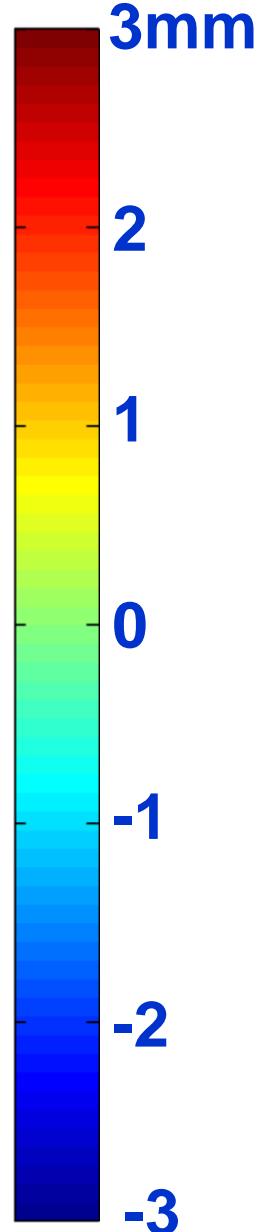
$$\Delta L_{\text{asymm}} = m f_g(e) \cdot [G_N \cdot \cos(\alpha) + G_E \cdot \sin(\alpha)]$$



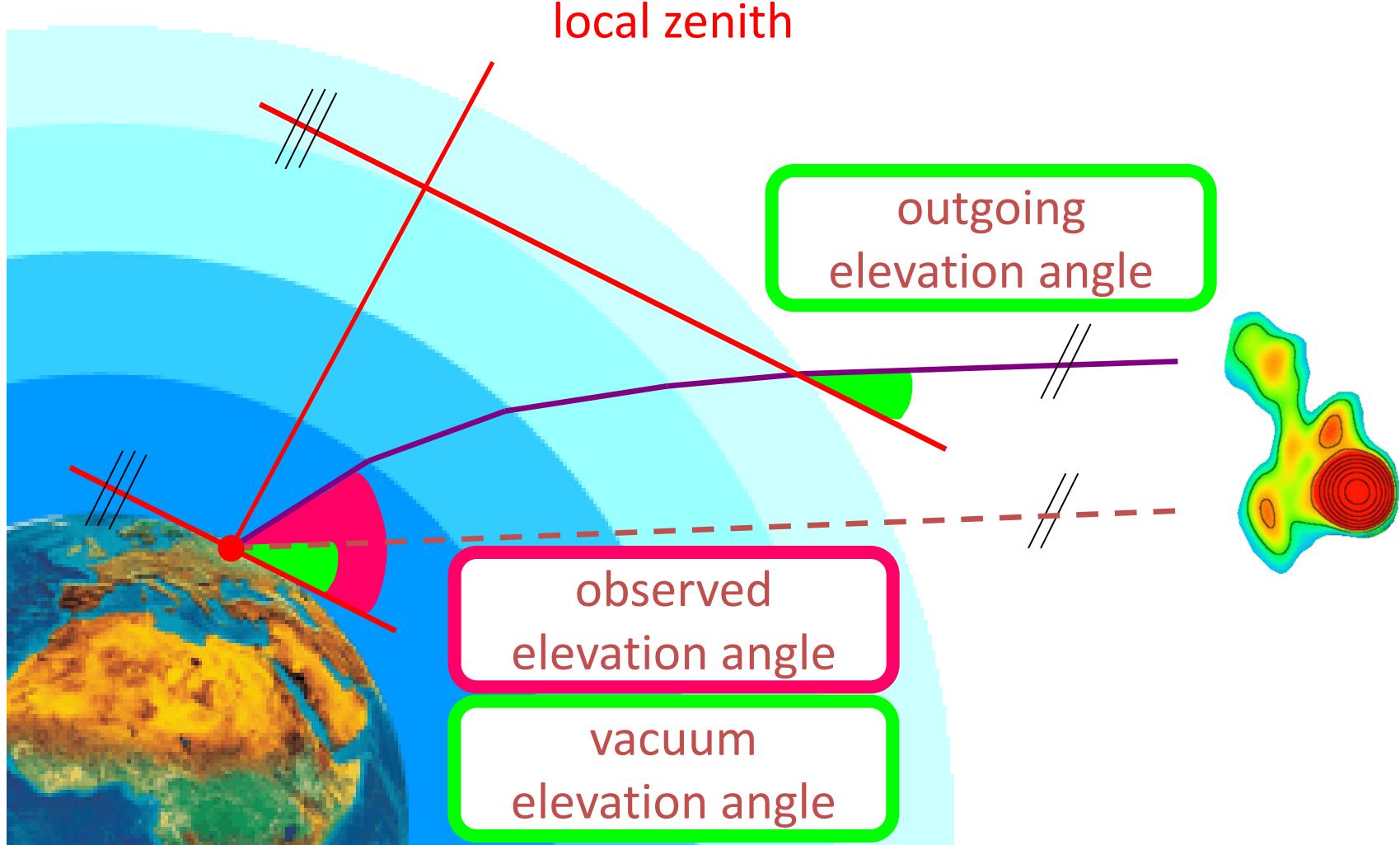
without modeling  
asymmetries



classical gradients  
applied



# Troposferin modellenmesinde ray-tracing



# Sayısal Atmosfer Modelleri (NWM)

- JMA-KARAT
- HIRLAM
- ECMWF

NWM	Modellerin kapsama alanı	Konum çözünürlüğü	Zamansal çözünürlük (saat)	Her profildeki seviye yüzeyleri sayısı
JMA-KARAT	Japan	0.1°	3	21
HIRLAM	Europe	0.2°	3	40
ECMWF	Global	0.25°	6	21

# Troposferin modellenmesinde ray-tracing (p,e,T)

inverse compressibility factors by adjustment to thermodynamic data (Owens, 1967)

$$Z_d^{-1} = 1 + p_d \left[ 57.97 \cdot 10^{-8} \left( 1 + \frac{0.52}{T} \right) - 9.4611 \cdot 10^{-4} \frac{t}{T^2} \right]$$

$$Z_w^{-1} = 1 + 1650 \frac{e}{T^3} \left[ 1 - 0.01317t + 1.75 \cdot 10^{-4} t^2 + 1.44 \cdot 10^{-6} t^3 \right]$$



Densities of dry air and water vapor

$$\rho_d = p_d \frac{m_d}{R} \frac{1}{T} Z_d^{-1}$$

$$\rho_w = e \frac{m_w}{R} \frac{1}{T} Z_w^{-1}$$

Total density  
 $\rho = \rho_d + \rho_w$

Hydrostatic and wet refractivities

$$N_h = k_1 \frac{R}{m_d} \rho$$

$$N_w = (k_2 \frac{e}{T} + k_3 \frac{e}{T^2}) Z_w^{-1}$$

R:universal gas constant

p<sub>d</sub>:partial pressure of dry air

e:water vapor pressure

t, T:temperature in Celsius and Kelvin

m<sub>d,w</sub>:molar masses of dry air and water vapor

k<sub>1</sub>,k<sub>2</sub>,k<sub>3</sub>,k<sub>2'</sub>:empirical coefficients by Bevis et al., 1994; Rüeger, 2002.

Troposphere delay along signal path, s

$$\Delta\tau_{trop} = 10^{-6} \int_0^{H_{trop}} [N_h(s) + N_w(s)] ds$$

$$\Delta\tau_{trop} = 10^{-6} \sum s_i (N_{hi} + N_{wi})$$

# Troposferin modellenmesinde ray-tracing ( $N_{hi}$ , $N_{wi}$ , $s_i$ , $\theta_i$ , $\varepsilon_i$ )

$$s_i = -r_i \sin \theta_i + \sqrt{r_{i+1}^2 - r_i^2 \cos^2 \theta_i} \quad ; \quad r_i = r_0 + h_i$$

$$z_{i+1} = z_i + s_i \sin \varepsilon_i$$

$$y_{i+1} = y_i + s_i \cos \varepsilon_i$$

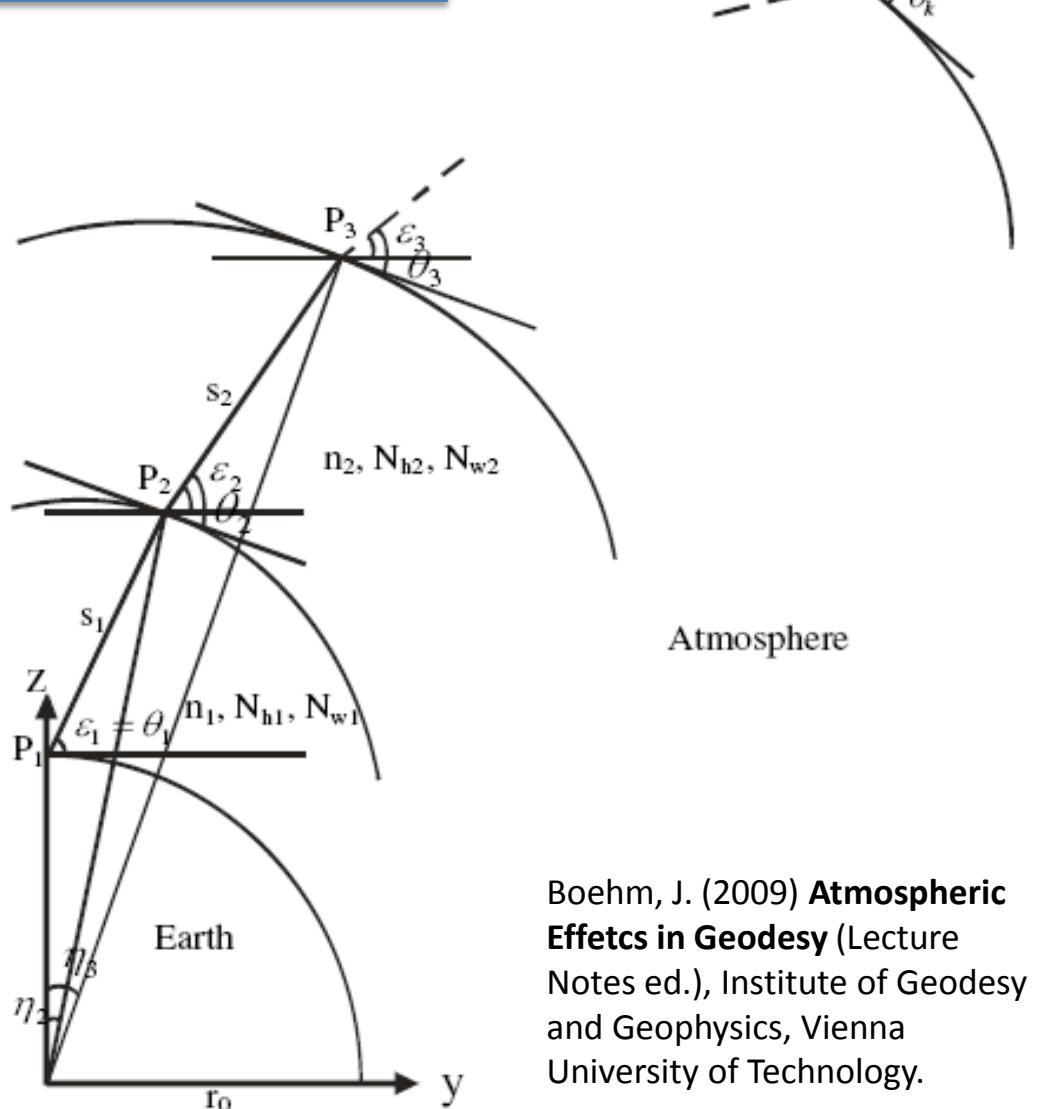
$$\eta_{i+1} = \arctan(y_{i+1} / z_{i+1})$$

$$\delta_{i+1} = \eta_{i+1} - \eta_i$$

$$n_i = 1 + (N_{hi} + N_{wi}) 10^{-6}$$

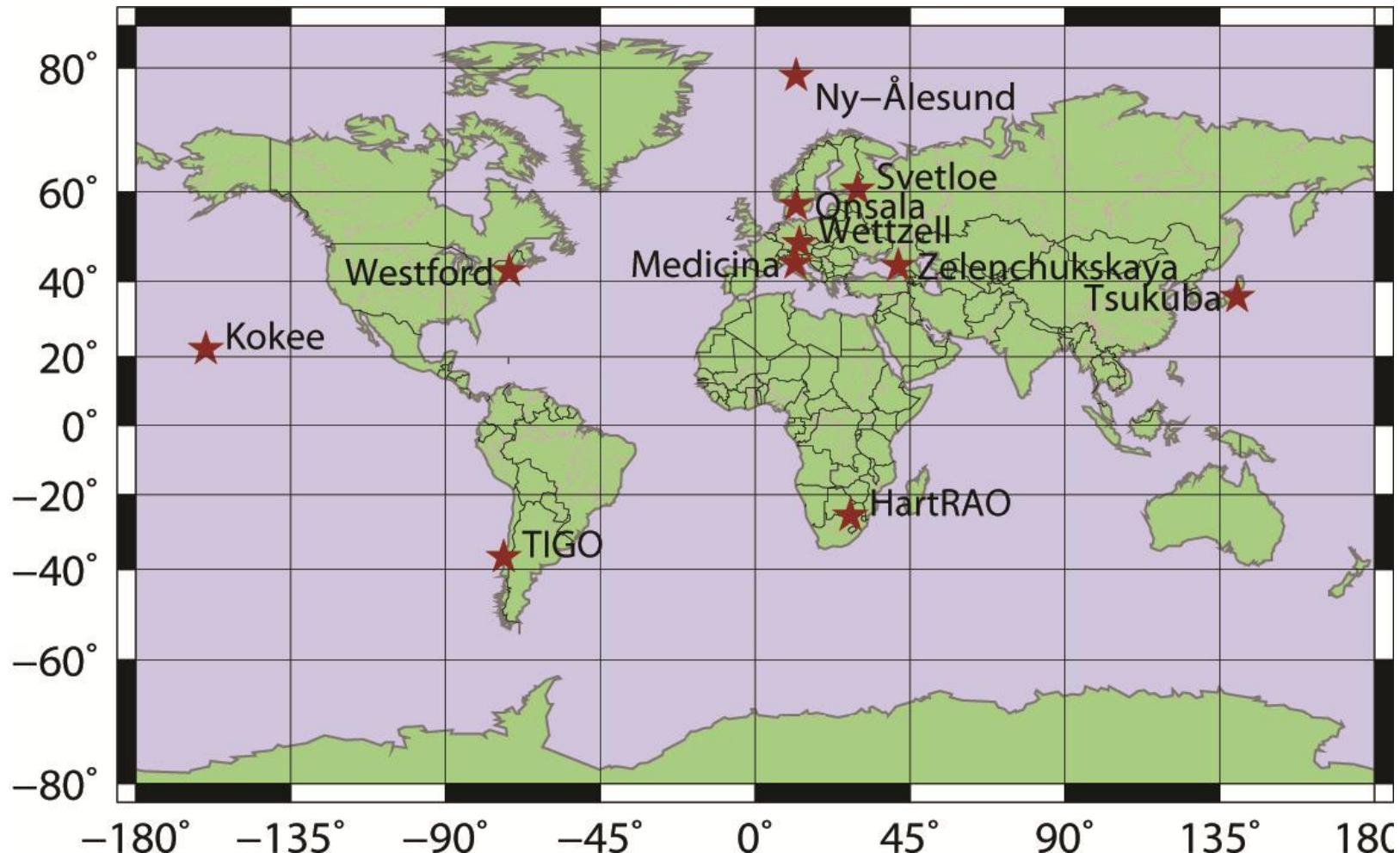
$$\theta_{i+1} = \arccos\left(\frac{n_i}{n_{i+1}} \cos(\theta_i + \delta_{i+1})\right)$$

$$\varepsilon_{i+1} = \theta_{i+1} - \eta_{i+1}$$



Boehm, J. (2009) **Atmospheric Effects in Geodesy** (Lecture Notes ed.), Institute of Geodesy and Geophysics, Vienna University of Technology.

# CONT08 ortak yerleşkeleri



İlk ölçü: Salı Agustos 12, 2008 @ 00:00:00 UT

Son ölçü: Salı Agustos 26, 2008 @ 23:59:59 UT

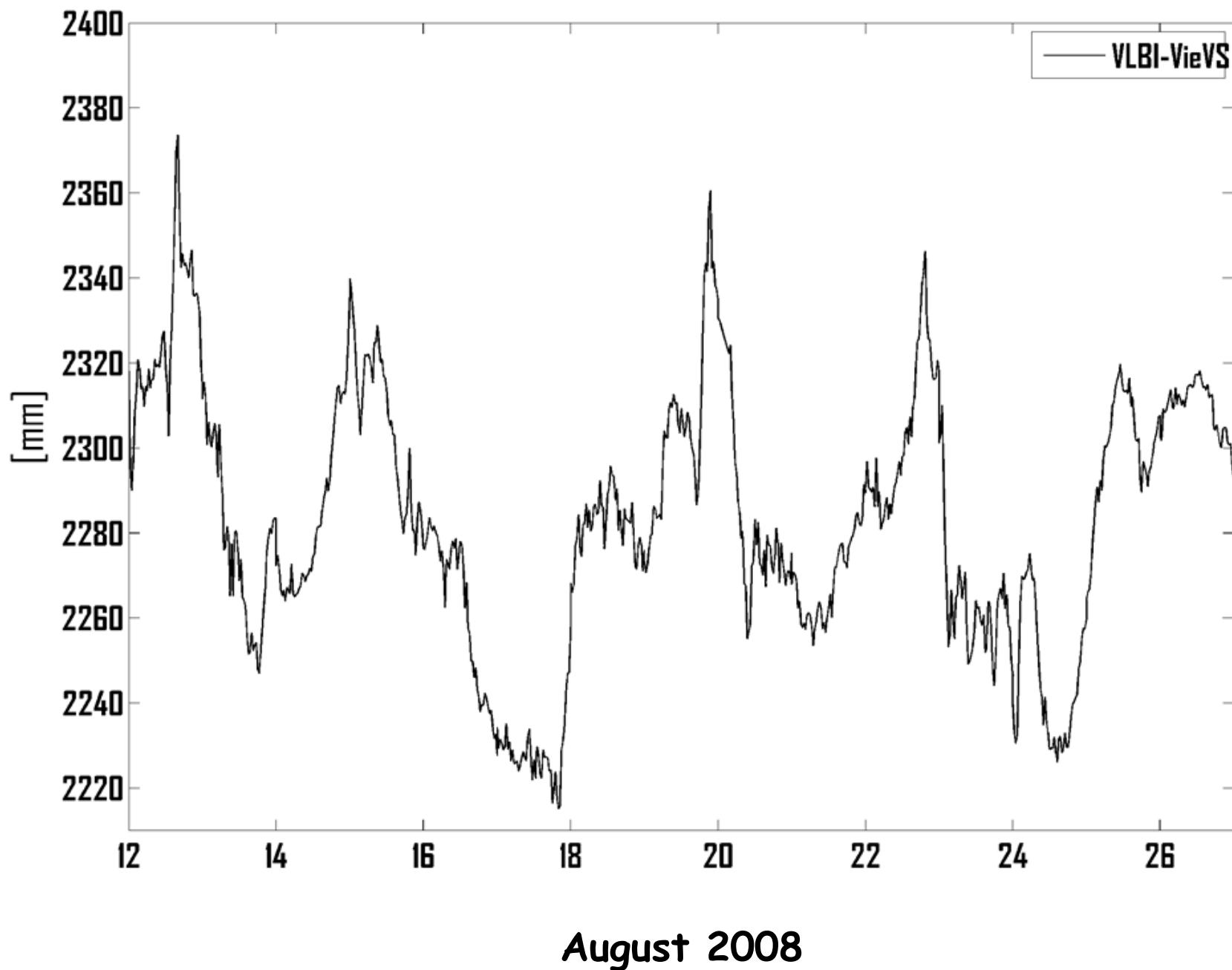
# Uyuşum ölçütleri

$$e.g. \quad x_i = ZTD_i^{VLBI-VieVS} \quad y_i = ZTD_i^{GPS-CODE} \quad \Delta_i = x_i - y_i$$

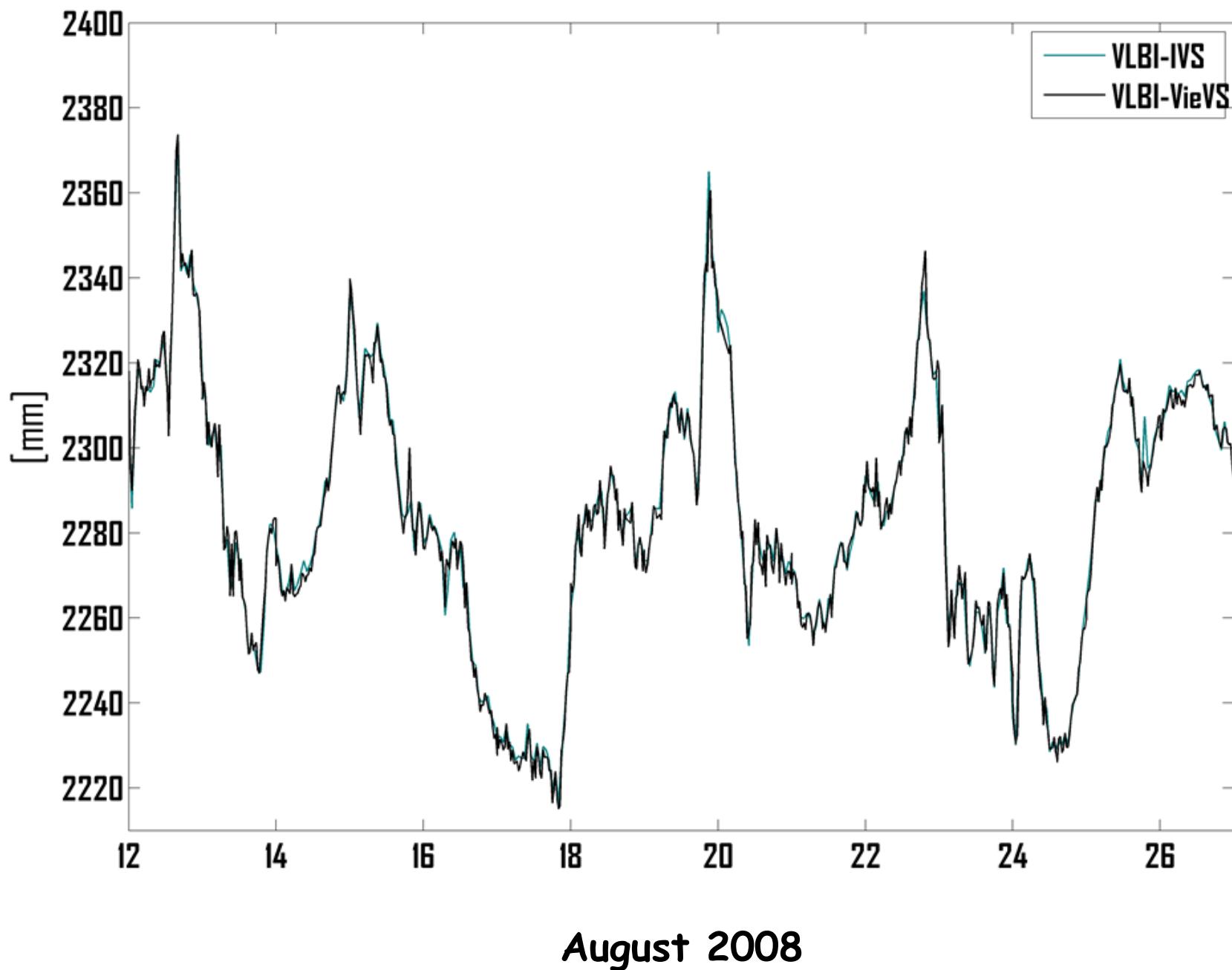
$$\bar{\Delta} = \frac{1}{n} \sum_{i=1}^n \Delta_i \quad i = 1, 2, \dots, n$$

$$Sx = [\frac{1}{n-1} \sum_{i=1}^n (\Delta_i - \bar{\Delta})^2]^{\frac{1}{2}}$$

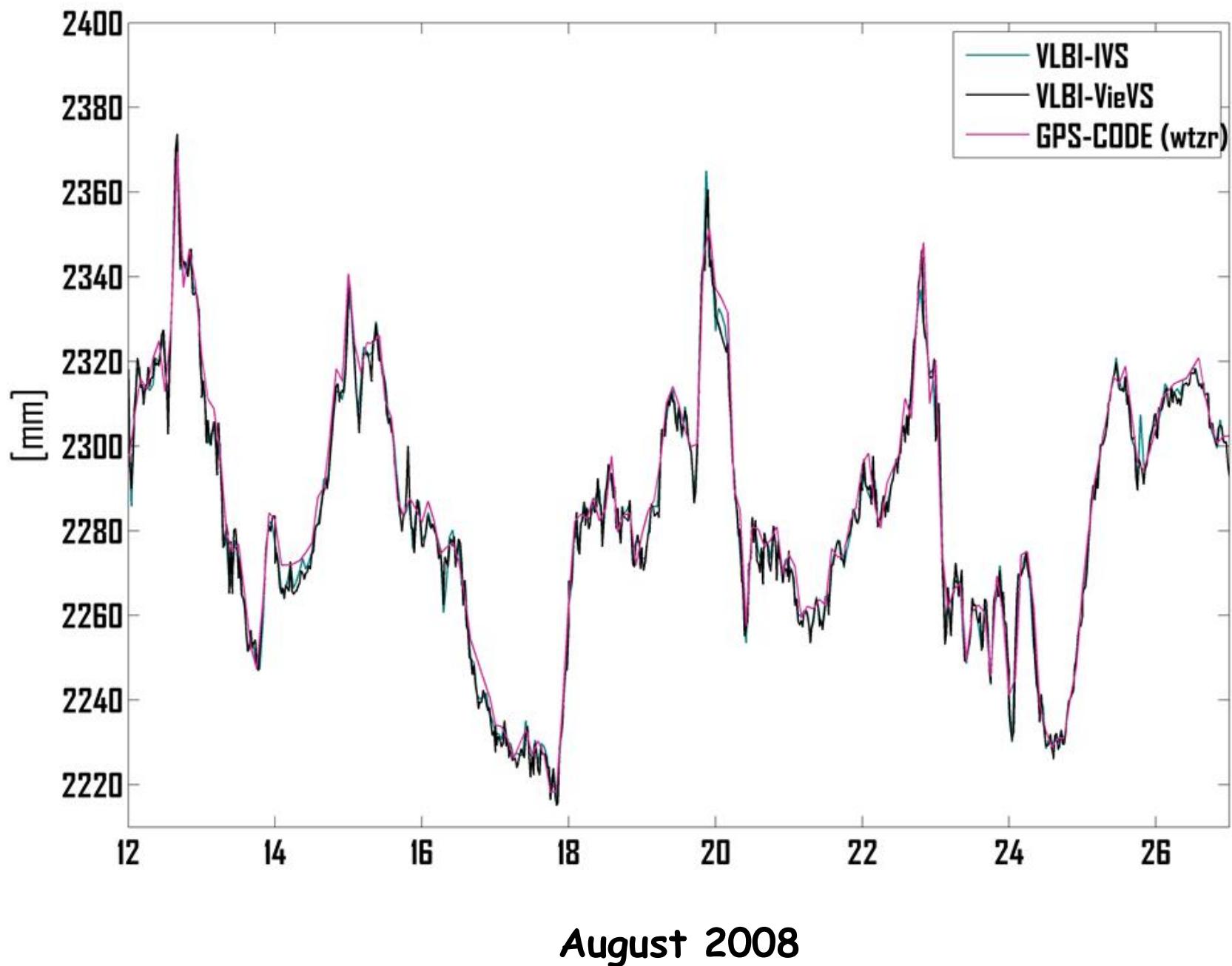
# WETTZELL (ZTD)



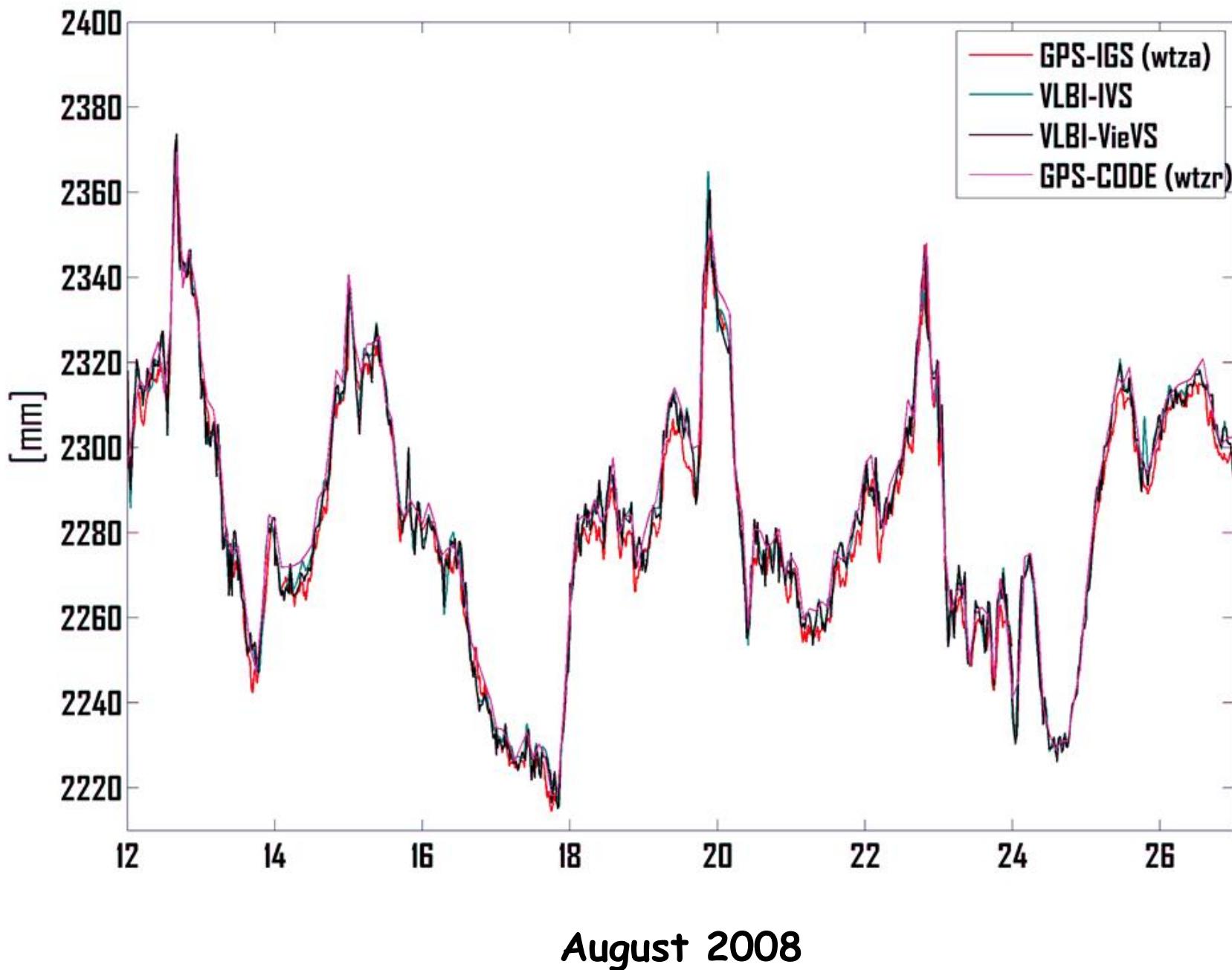
# WETTZELL (ZTD)



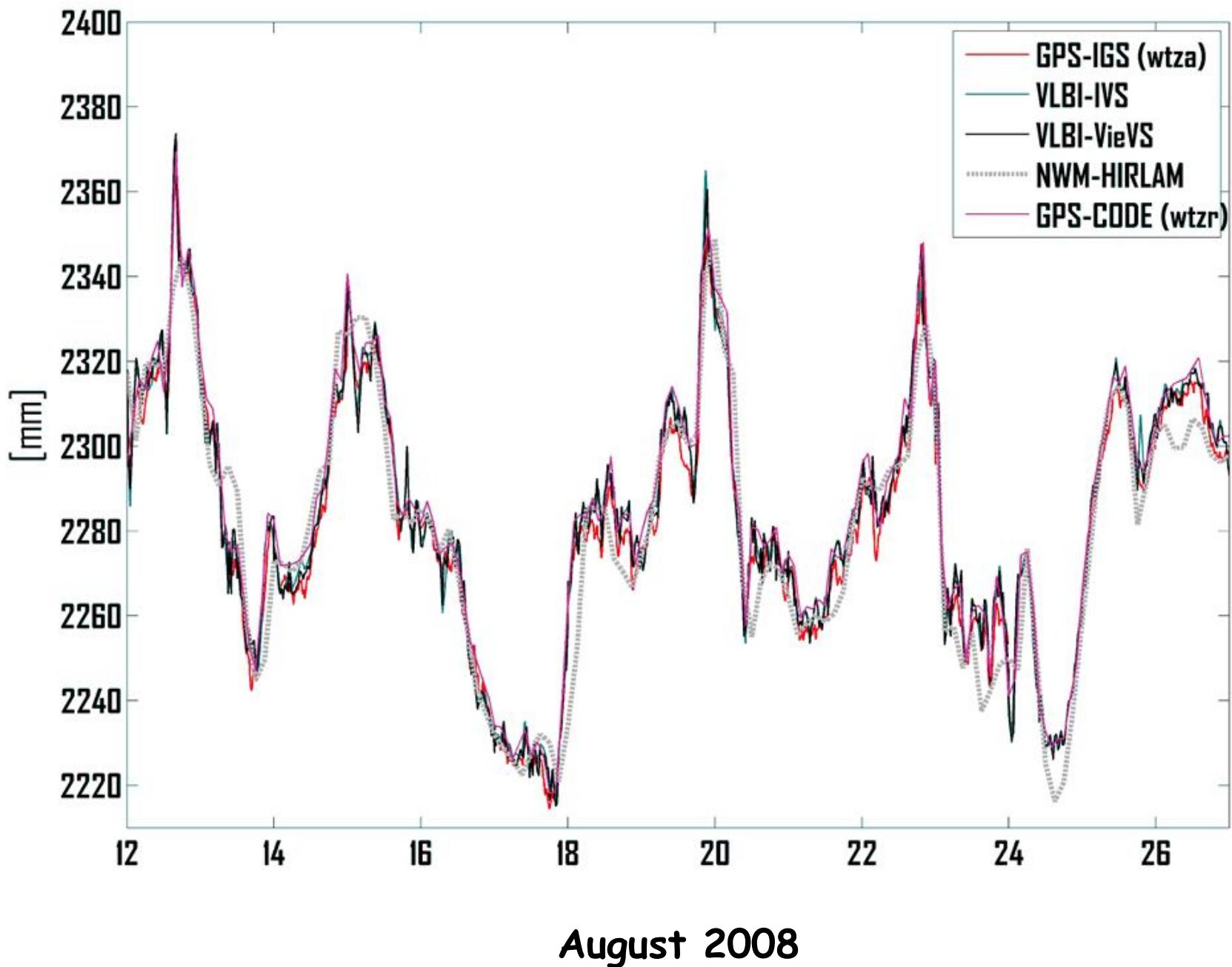
# WETTZELL (ZTD)



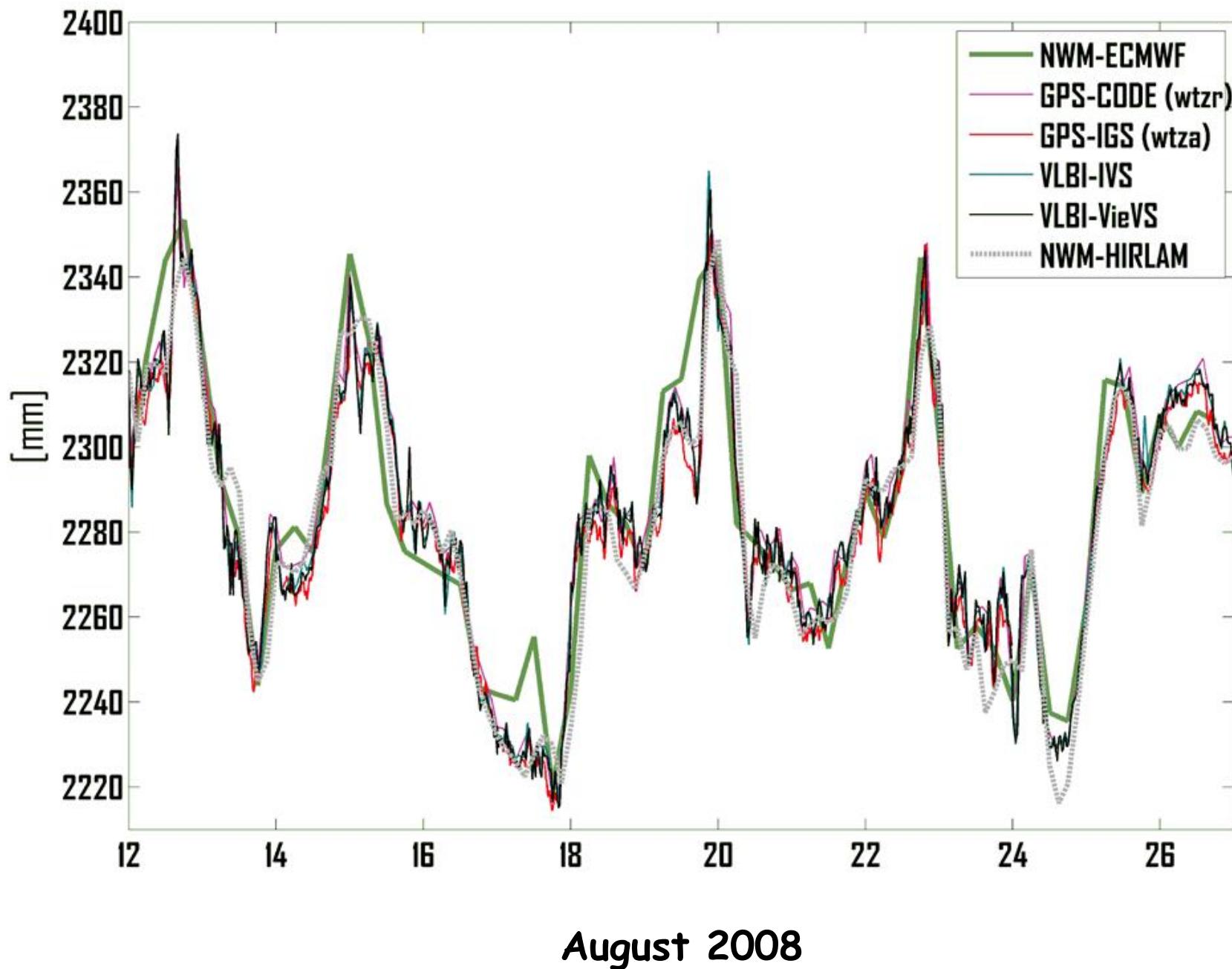
# WETTZELL (ZTD)



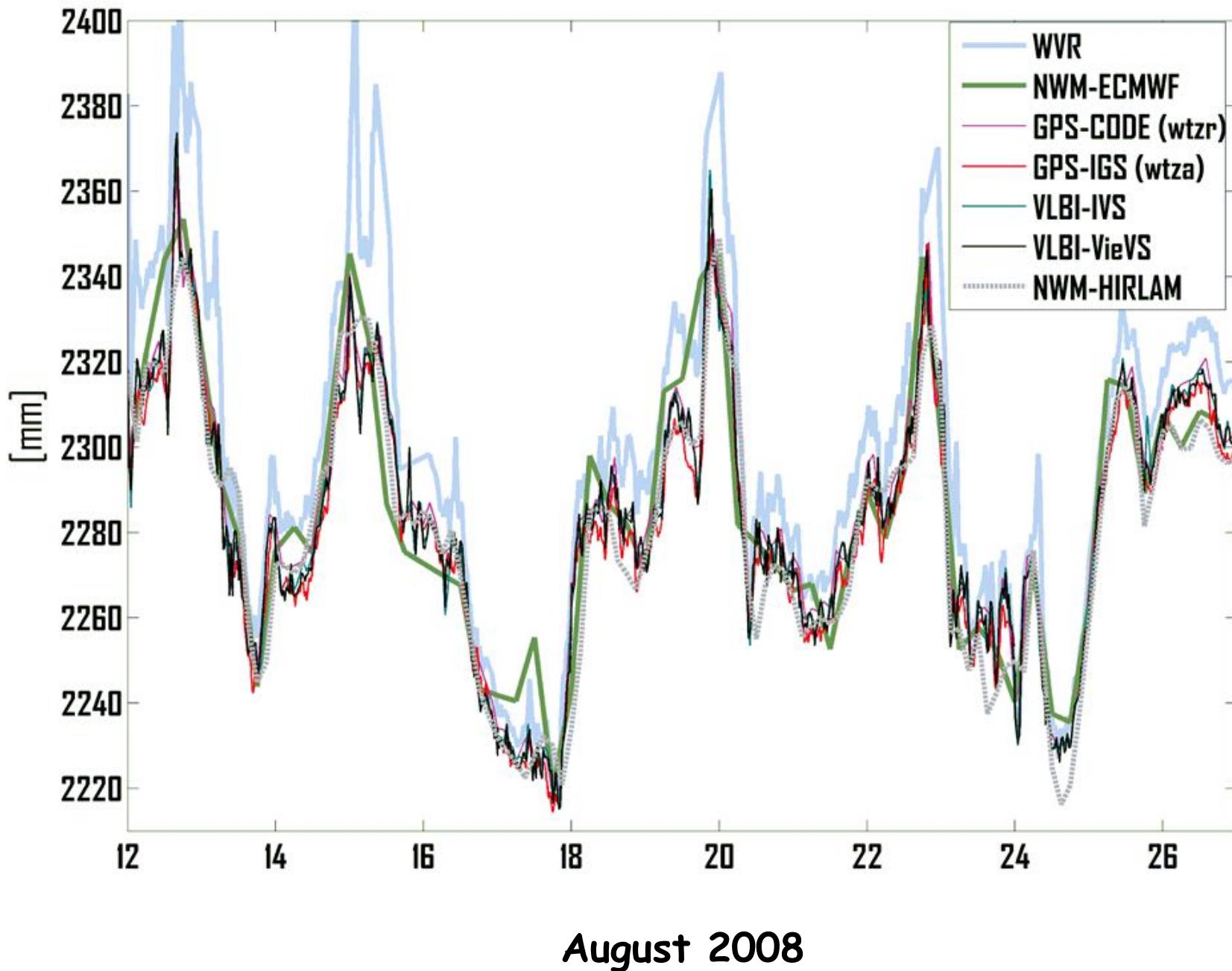
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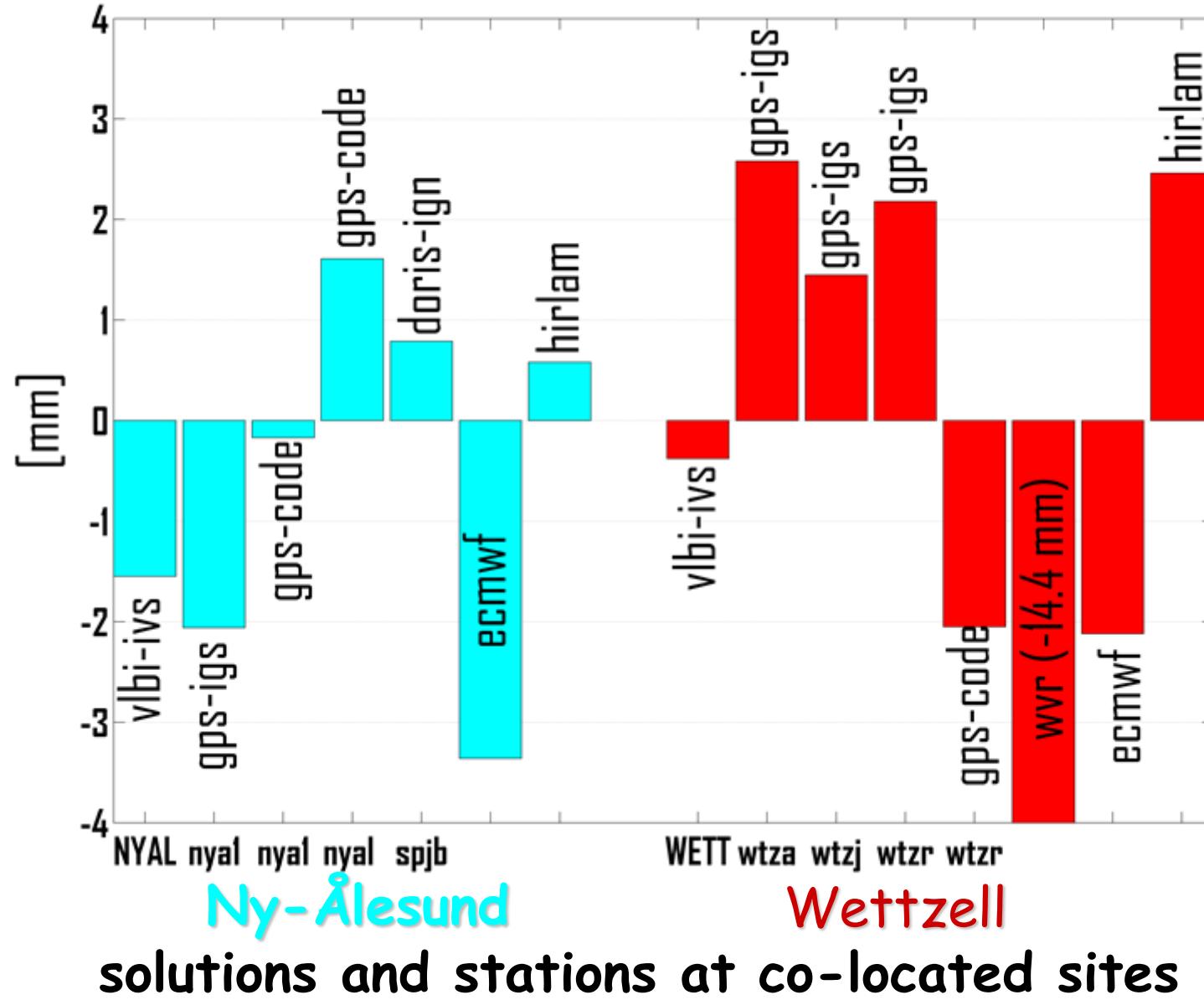
# WETTZELL (ZTD)



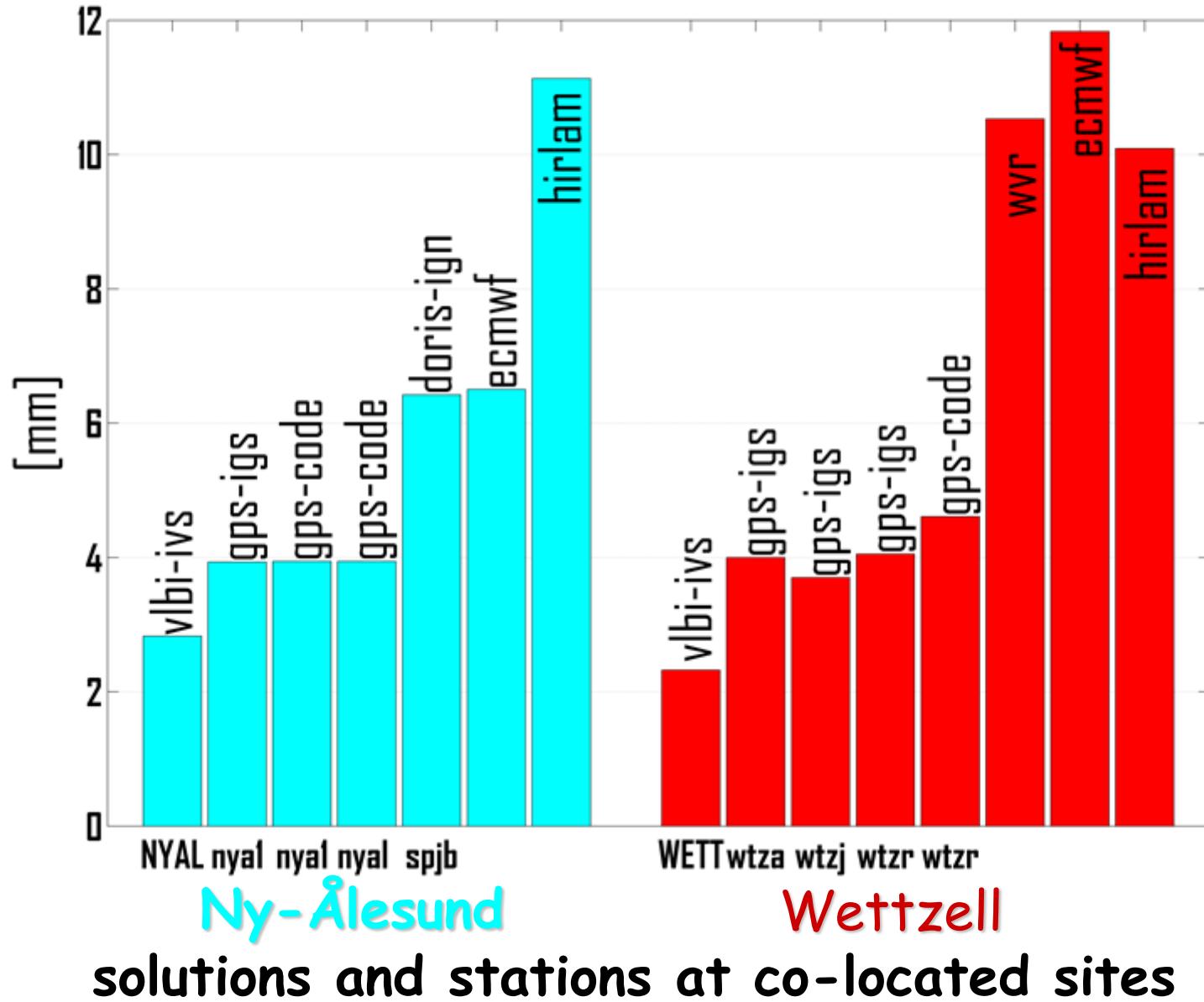
# WETTZELL (ZTD)



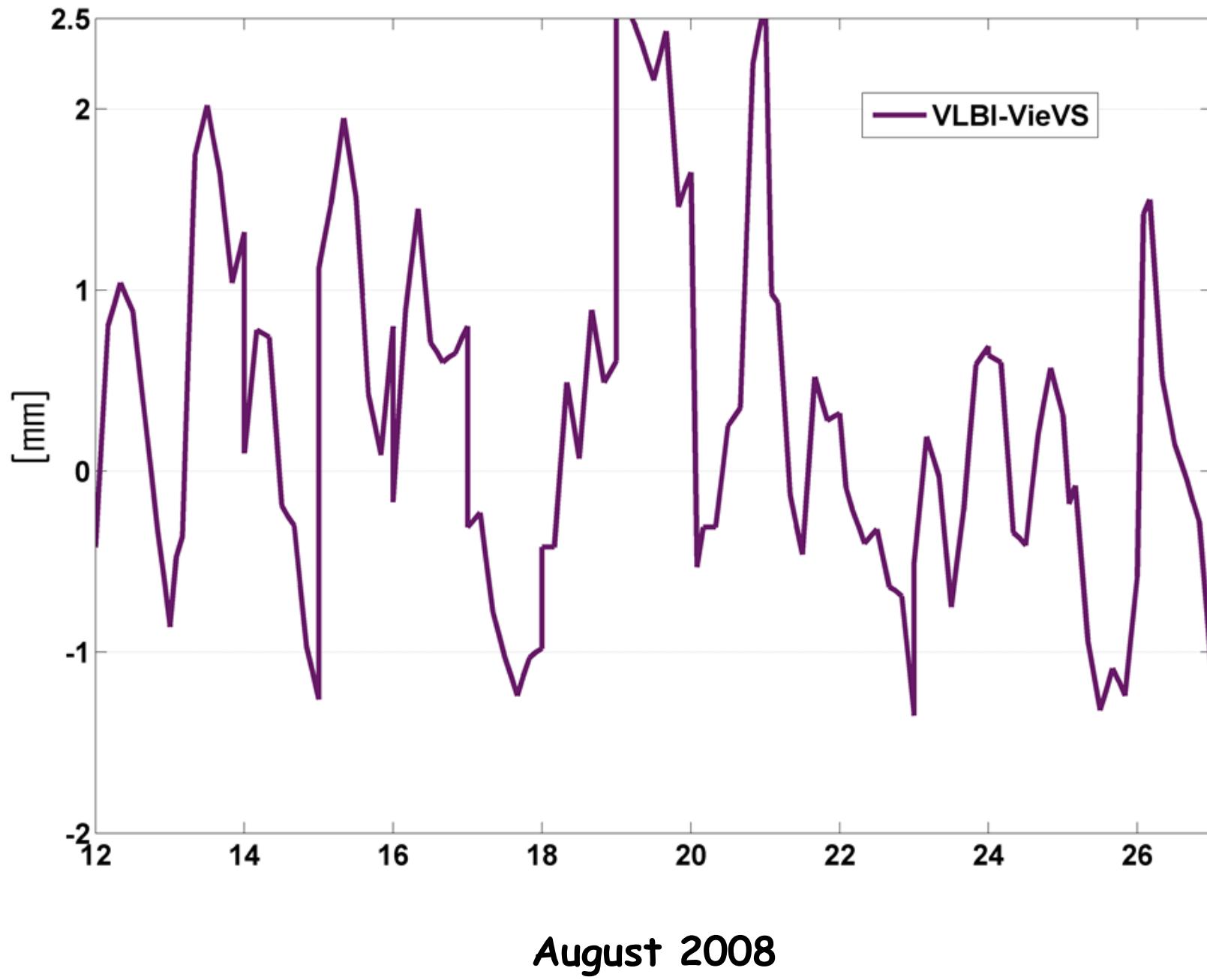
# ZTD - VieVS ve diğer çözümler arasındaki offsetler



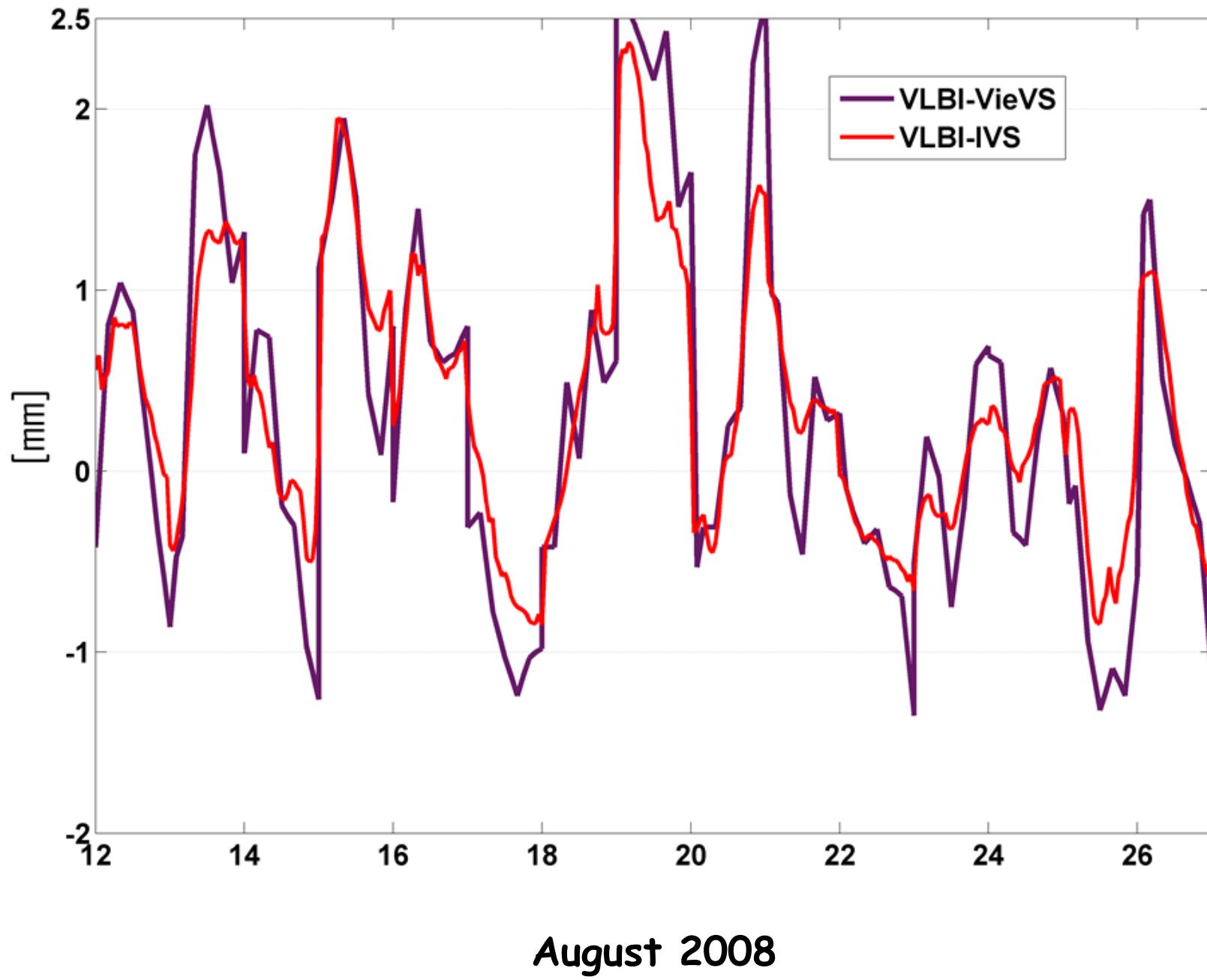
# ZTD - VieVS ve diğer çözümler arasındaki standart sapmalar



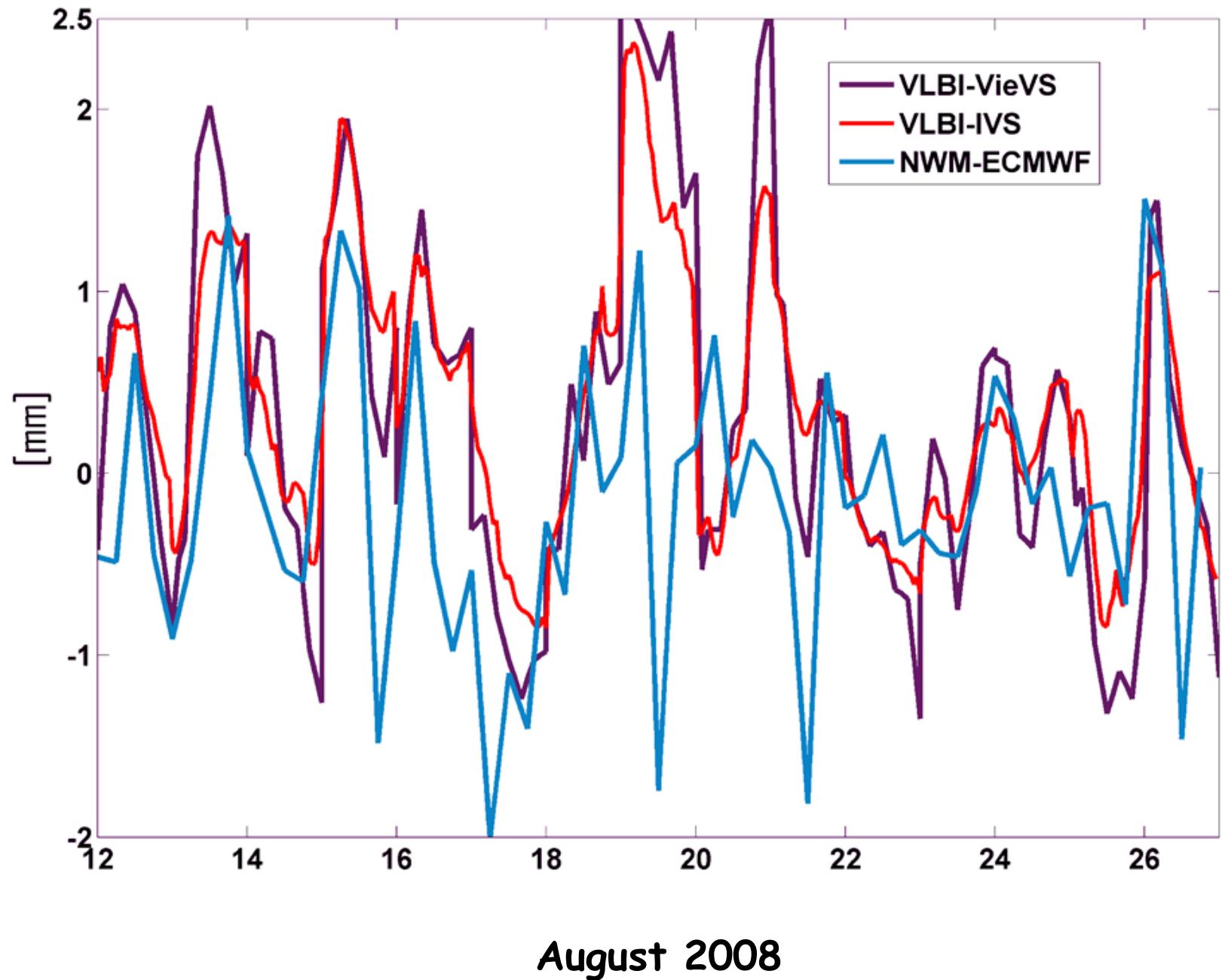
# TSUKUBA (Troposphere north gradients)



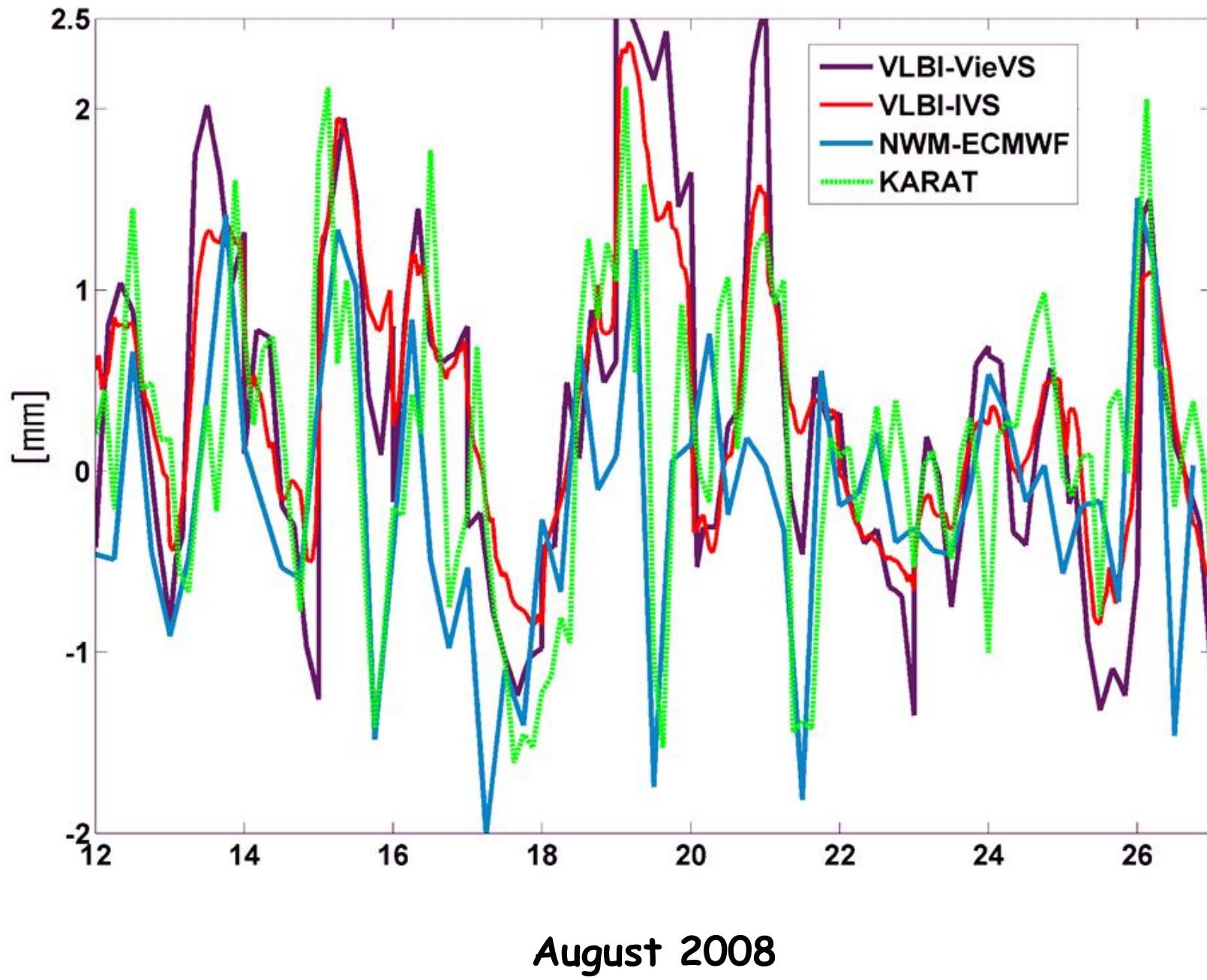
# TSUKUBA (Troposphere north gradients)



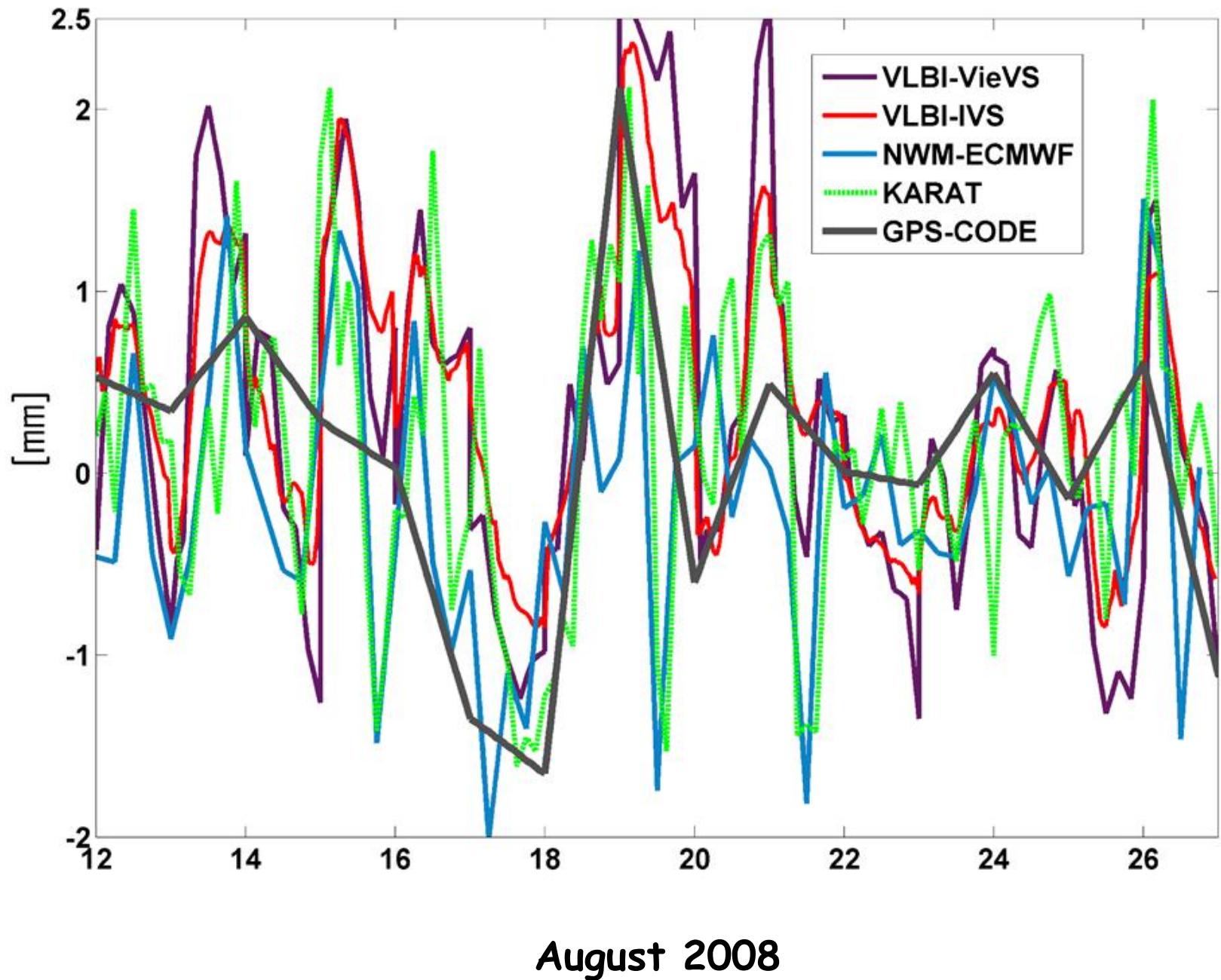
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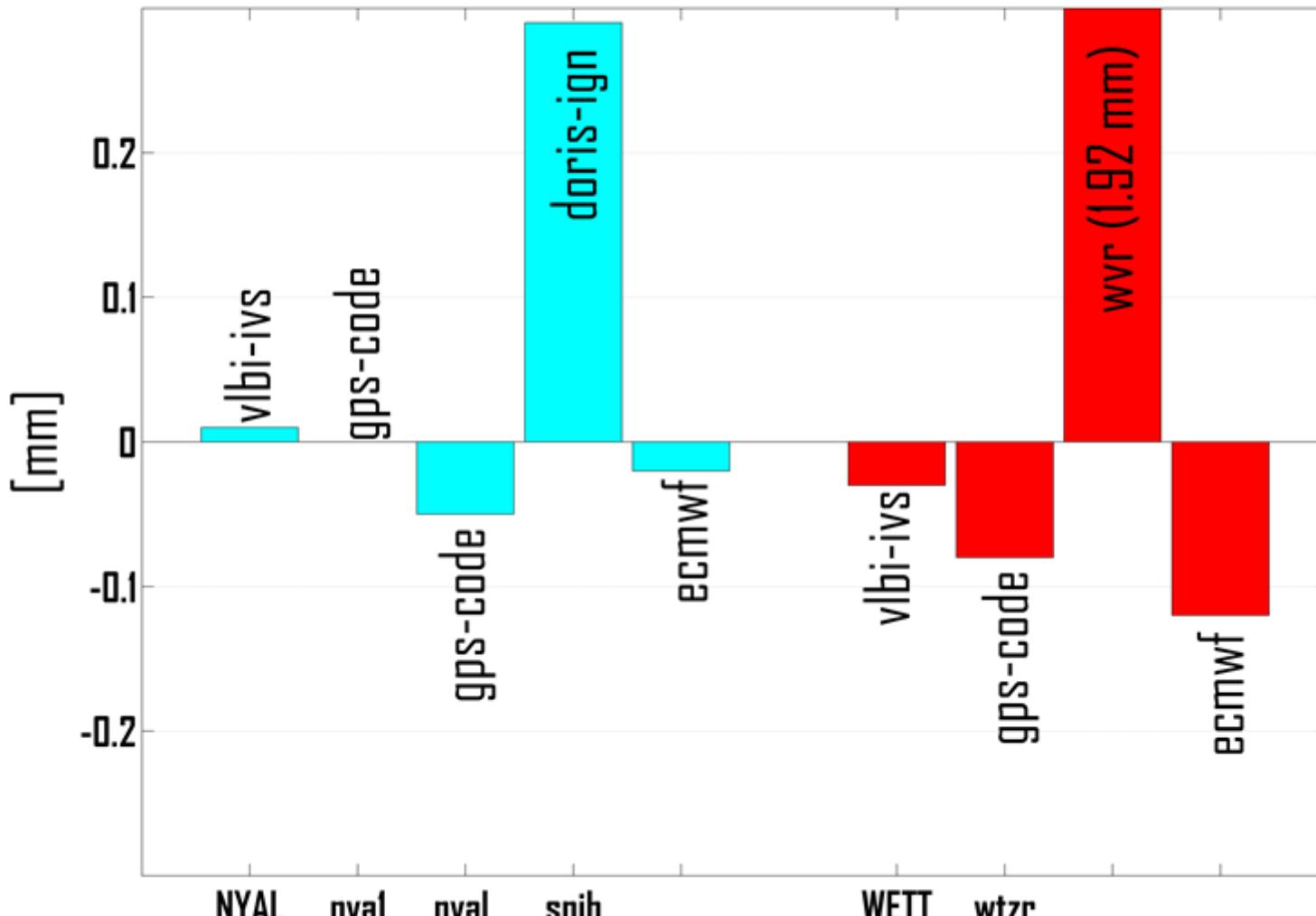


# TSUKUBA (Troposphere north gradients)



# Troposfer kuzey gradyanları

VieVS ve diğer çözümler arasındaki offsetler



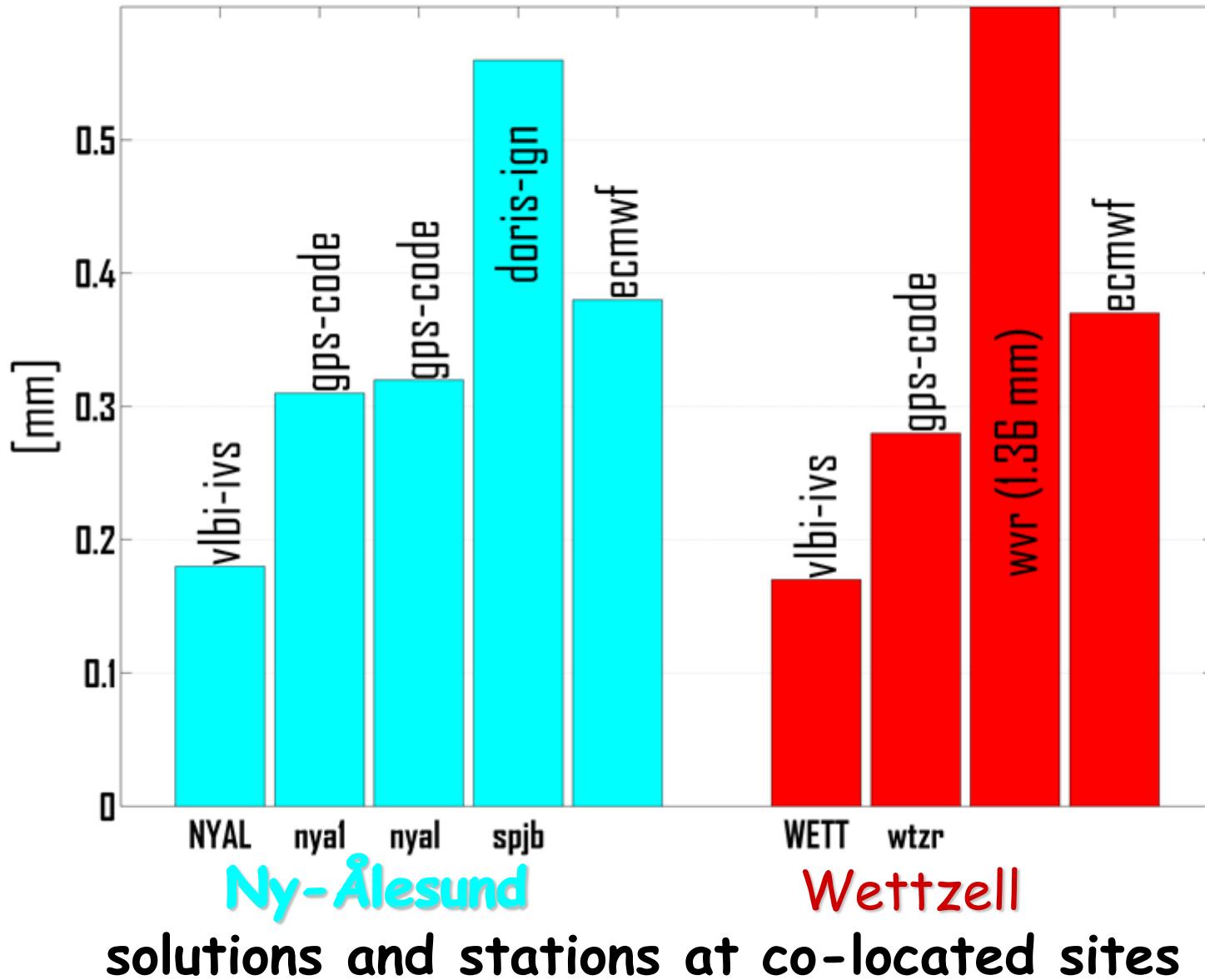
Ny-Ålesund

Wettzell

solutions and stations at co-located sites

# Troposfer kuzey gradyanları

VieVS ve diğer çözümler arasındaki standart sapmalar



# Sonuçlar

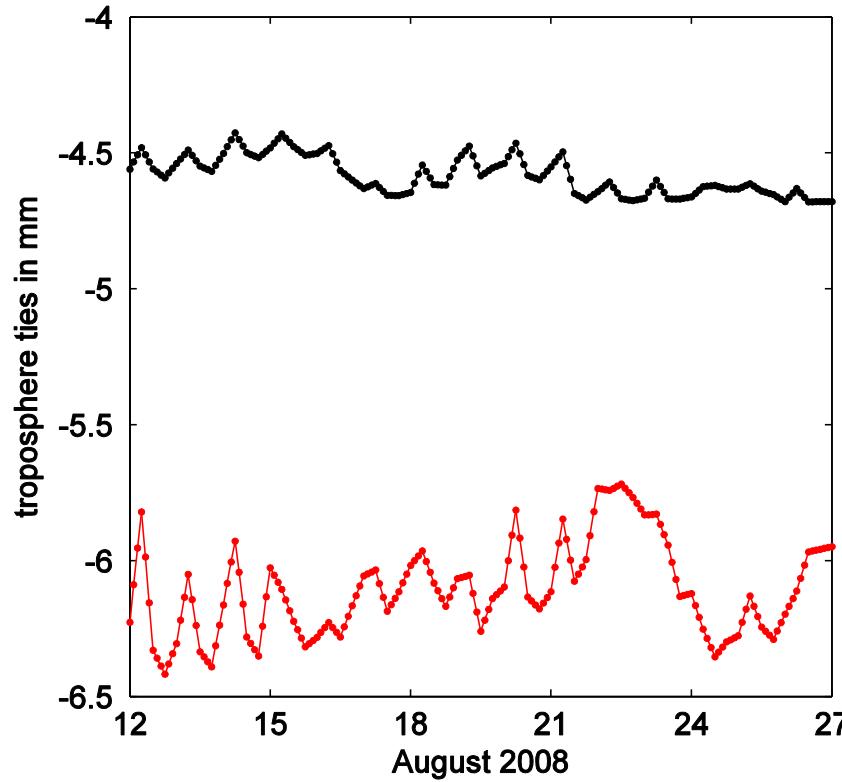
- Uzay Jeodezi teknikleri (VLBI, GPS, DORIS) ölçülerinin analizlerinden (VieVS, IVS, IGN, IGS, CODE) elde edilen zenit sinyal gecikmeleri genellikle 0.5-1 cm aralığında uyuşum göstermektedirler.
- Uzay Jeodezi tekniklerinin zenit sinyal gecikmeleri ile diğer teknikler/modellerden elde edilenler (WVR, ECMWF, HIRLAM, JMA-KARAT) arasındaki farklar 2 cm nin altındadır. Korelasyon katsayıları genellikle  $> 0.9$  (sunumda gösterilmedi).
- Zenit sinyal gecikmelerinde ve gradyanlarda en iyi uyum teknik-içi (intra-teknik) analizlerden elde edilmiştir (VieVS ve IVS, CODE ve IGS).
- Teknikler-arası (inter-teknik) hem zenit sinyal gecikmelerinde hem de gradyanlarda en iyi uyum VLBI ve GPS arasındadır.
- Tekniklerden elde edilen gradyanlar arasındaki korelasyonlar 0.6'nın altında kalmıştır (sunumda gösterilmedi).

**Uluslararası servislere ölçü dosyalarını  
sagladıkları için teşekkür ederiz !**

**Katılımınız ve dinledığınız için  
teşekkür ederiz !**

# Troposphere ties

- The reference height were selected as the VLBI reference points heights.
- The troposphere ZTD ties were calculated at each common epoch.



Troposphere ties between the GPS antenna TSKB and the VLBI antenna TSUKUB32 during IVS-CONT08, calculated for all common epochs. Red and black dotted lines illustrate total and hydrostatic ties, respectively.

# Calculation of troposphere ties (Brunner and Rüeger, 1992)

$$p = p_0 \left(1 - \frac{\gamma(H - H_0)}{T_0}\right)^{\frac{g}{\gamma R_L}}$$

$$\Delta ZHD = \frac{0.0022768(p - p_0)}{1 - 0.00266 \cos(2\phi_0) - 0.28 \times 10^{-6} H_0}$$

$$\Delta ZWD = \frac{-2.789 e_0}{T_0^2} \left( \frac{5383}{T_0} - 0.7803 \right) \gamma(H - H_0)$$

$H_0$  : Reference height (VLBI reference point height),

$e_0$  : Water vapor pressure (hPa) at the reference height,

$p_0$  : Total pressure (hPa) at the reference height,

$T_0$  : Temperature (Kelvin) at the reference height,

$H$  and  $p$  : The height and total pressure at the co-located site,

$\gamma = -0.0065 \text{ K m}^{-1}$  (average temperature lapse rate),

$R_L = 287.058 \text{ m}^2 \text{ s}^{-2} \text{ K}^{-1}$  (specific gas constant),

$g$  = the gravity in  $\text{m s}^{-2}$ ,

$\phi_0$  = latitude of the co-located site in degrees.

# Very Long Baseline Interferometry (VLBI)

- Vienna VLBI Software (VieVS):

- NNT/NNR on ITRF2005.
- VMF1, above  $5^{\circ}$ .
- 0.7 picosec $^2$ /sec for ZTDs (relatively loose).
- 2 mm/day for gradients (relatively loose).
- 30 minutes for ZTDs, and 120 for gradients.
- APL applied a priori (Petrov and Boy, 2004)

- International VLBI Service for Geodesy and Astrometry (IVS):

- Intra-technique combined solution for ZTDs and troposphere gradients.
- 60 minutes for ZTDs and for gradients

# Global Positioning System (GPS)

- Center for Orbit Determination in Europe (CODE)

- Bernese GPS software.
- NNR on IGS05.
- 120 minutes interval for ZTDs and 24 h for gradients.
- VMF1,  $3^\circ$  + elevation dependent weighting.
- No constraints for zenith delays and gradients.
- APL applied.

- International GNSS Service (IGS)

- GIPSY/Oasis software.
- PPP solution, Kalman filter.
- IGS final combined : orbits, clocks, and EOP.
- NMF,  $7^\circ$ .
- 5 minutes for ZTDs.
- Estimated parameters are: clocks, station position, zenith wet delay, troposphere gradients, phase biases (Byun S.H. and Bar-Sever Y.E., 2009).

# Doppler Orbitography and Radio Positioning Integrated by Satellite (DORIS)

- Institut Géographique National (IGN)
  - Software is GIPSY/Oasis.
  - TRF is fixed to ign09d02.
  - VMF1, 10°.
  - DORIS reset at no regular interval.
  - It is reset at start of pass and only if the previous reset is 20 minutes before or earlier.
  - ZTD epochs interpolated linearly from the irregular epochs to 120 minutes (epochs at UTC integer hours).
  - No interpolation between the data gaps larger than 60 minutes.
  - Co-located sites are Ny-Ålesund (spjb), Kokee Park (kolb), Hartebeesthoek (hbmb).

# Water Vapor Radiometer (WVR)

- Slant wet delays inferred from measurements of the sky brightness temperature at about 22 GHz and 31 GHz.
- ZWDs and gradients obtained by a least-squares fit. 30 minutes estimation interval for ZWDs and 120 minutes estimation intervals for troposphere gradients.
- ZHDs calculated from surface pressure measurements at the VLBI antenna.
- Cut off  $20^\circ$ .
- Data acquired during rain removed.
- Co-located sites: Wettzell, Tsukuba, and Onsala.